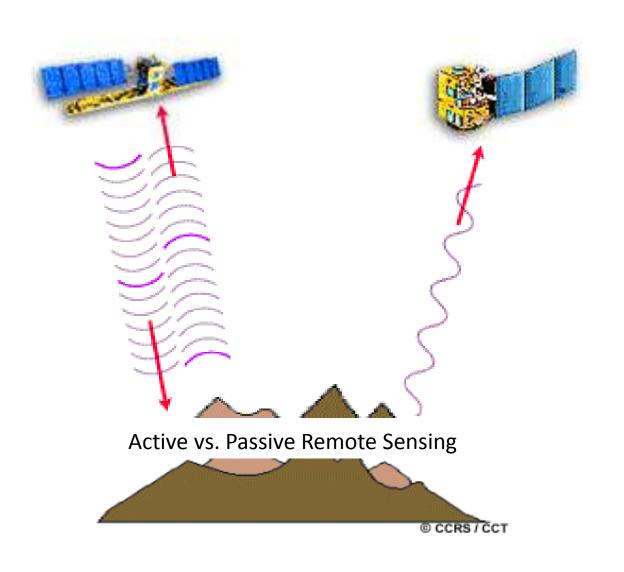
Session 3 (1 hr): Prof. Susan L. Ustin

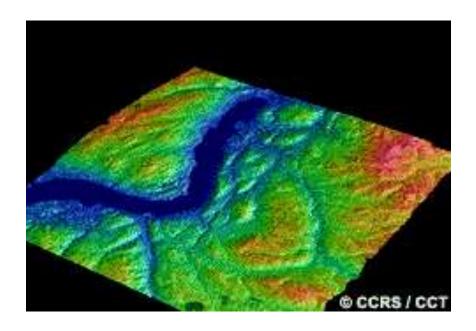
Title: Remote sensing using active RaDAR and LiDAR for hydrologic properties and processes

Contact me at: slustin@ucdavis.edu



LiDAR and RaDAR Principles





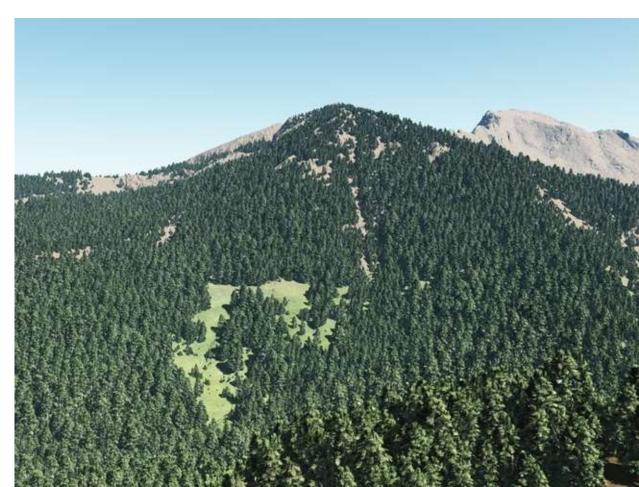


Real Forest landscape

LiDAR simulated forest

Qinghua Gao, UCM and Maggi Kelly, UCB

Airborne Lidar measured over forested mountain landscape



Main Application for Lidar and RaDAR is Creating Maps of Surface Topography

90m SRTM DEM Data

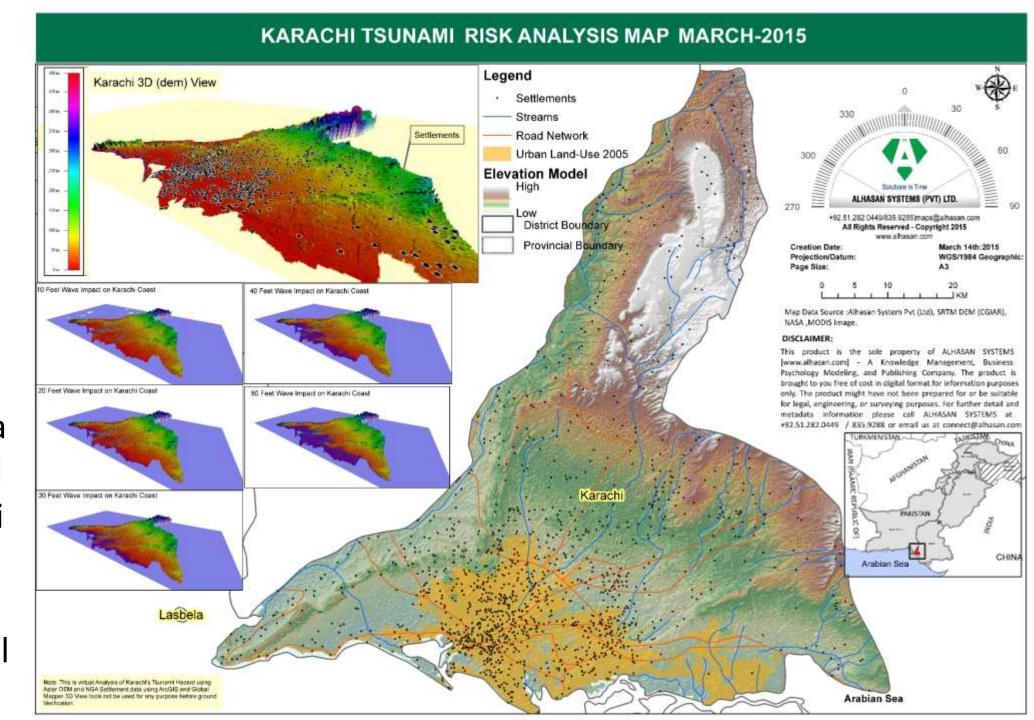
ASTER version 3 DEM (at 30m) with Landsat overlayed



Example of using ASTER, a 14 band imager from JAXA, located on the NASA Terra platform.

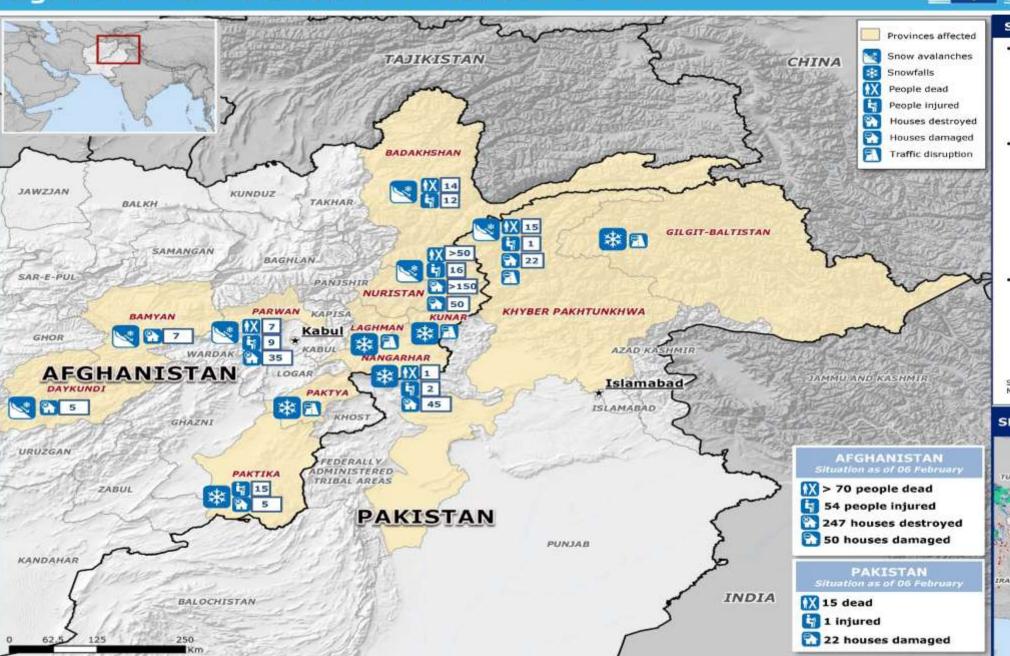
DEM to create a Tsunami Hazard Map for Karachi

Application for Global Sea Level Rise?



Emergency Response Coordination Centre (ERCC) – ECHO Daily Map | 06/02/2017 Afghanistan and Pakistan – Snow avalanches





Copyright, European Union, 2017. Map created by EC-JRC/ECHO. The boundaries and names shown on this map do not imply official endorsement or acceptance by the European Union

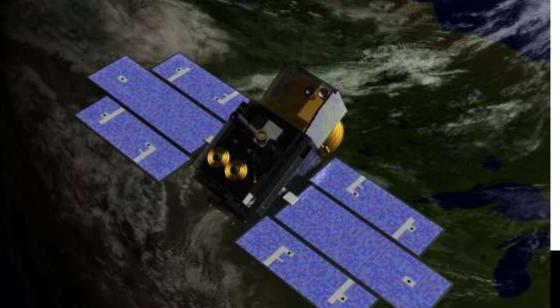
SITUATION

- Severe weather, including heavy rain and snowfalls, has been affecting the central and northeastern provinces of Afghanistan and the northern provinces of Pakistan, causing casualties and damages.
- As of 6 February, national authorities reported at least 85 people dead, of which 70 in Afghanistan and 15 in Pakistan, over 245 houses destroyed in Afghanistan and at least 72 houses damaged throughout the affected areas. Traffic disruptions have also been reported.
- Over the next 72 h, cloudy to overcast conditions are to prevail over the areas affected by snow avalanches, with light to locally medium intensity precipitation phenomena (mainly snowfalls).

Sources: DG ECHO, UN OCHA, Government of Pakistan, Meteocentre, ECMWF, Media

SNOW COVERAGE (04-06 Feb, MODIS)



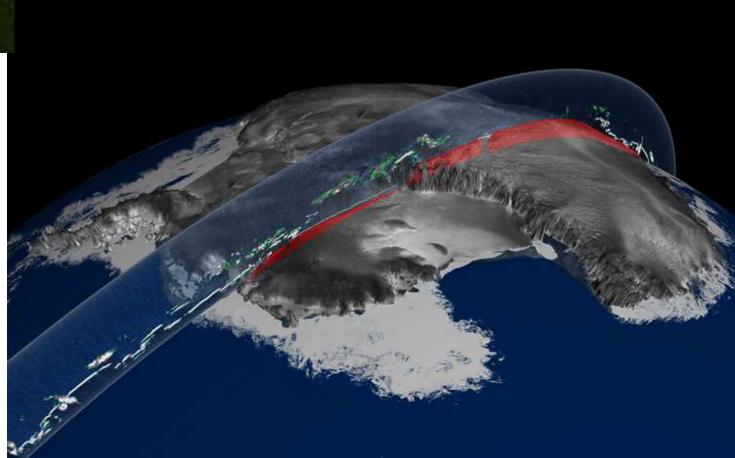


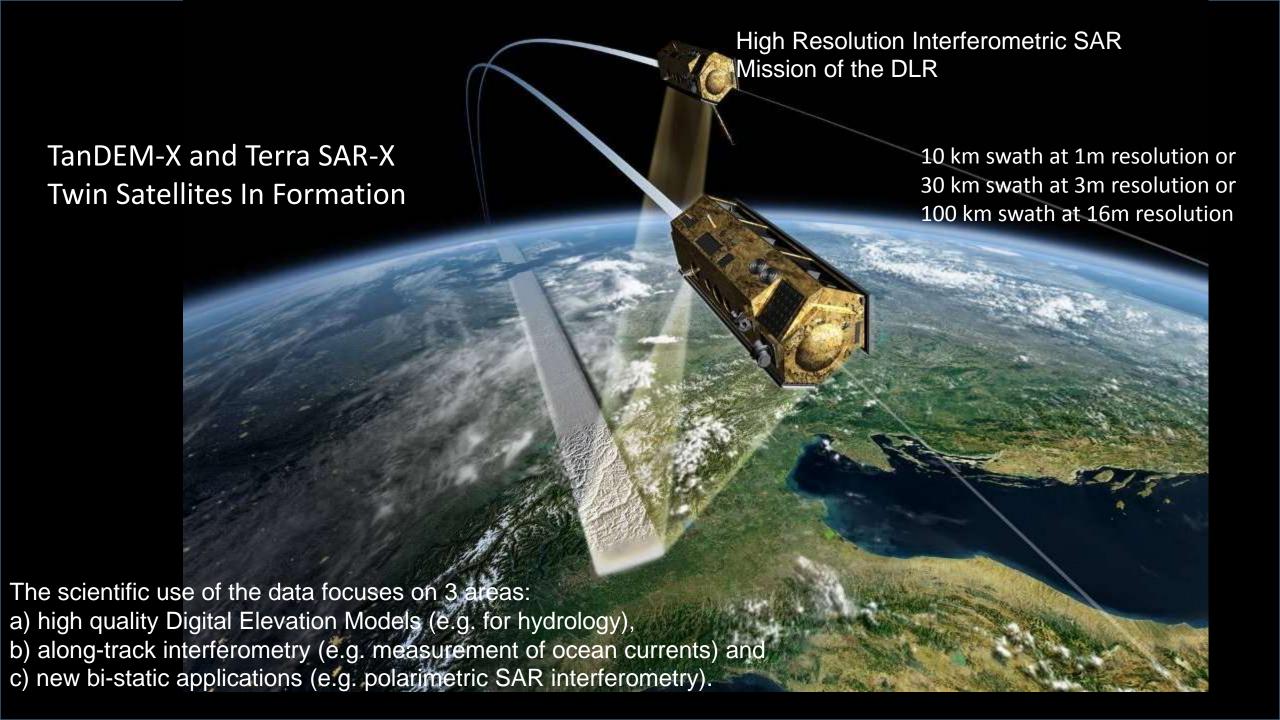
Ice, Cloud and Land Elevation Satellite (ICESat)

IceSat 2 Scheduled for launch in 2017

Measures:

- 1. ice sheet mass balance, cloud and aerosol heights
- 2. land surface topography and vegetation characteristics

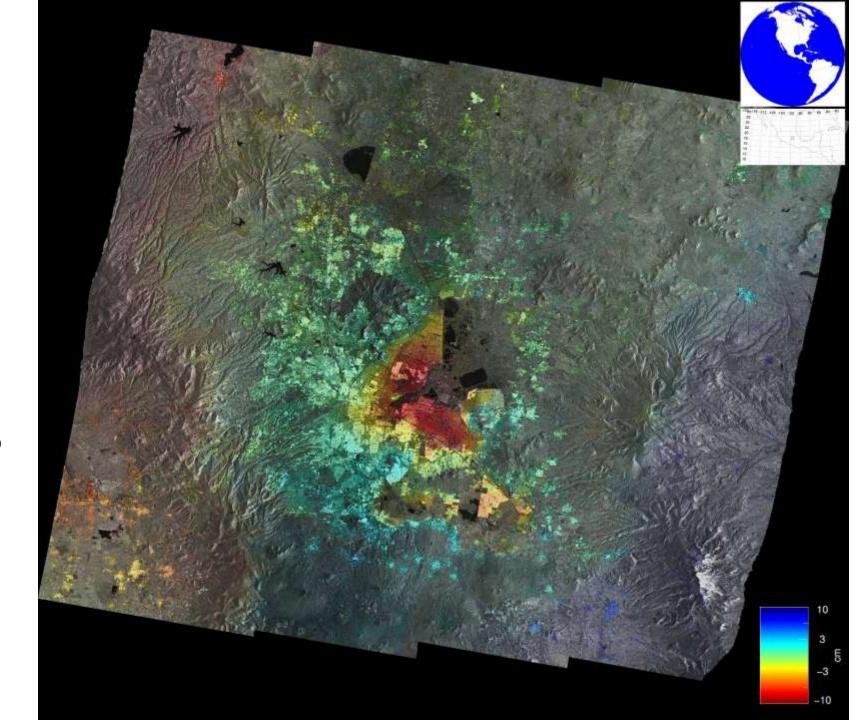


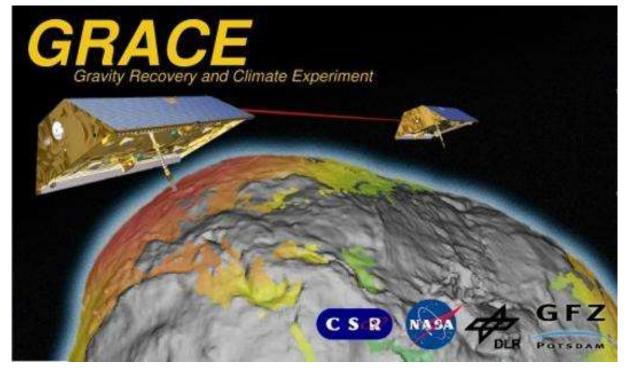


Changes in ground height of Mexico City over a 4 month period, 20 Sept. 2009 to 30 Jan. 2010, as measured by TanDEM-X.

Changes here are primarily due to groundwater extraction.

The TanDEM-X system is designed to build the "WorldDEM" to a vertical accuracy of 2m (relative) and 4m (absolute), with a horizontal raster of approximately 12x12 square meters. This meets **HRTE-3** (High Resolution Terrain Elevation, level-3) also called DTED 3.





The Gravity Recovery and Climate Experiment Follow-on (GRACE-FO) mission is a partnership between NASA and the German Research Centre for Geosciences (GFZ).

GRACE-FO will follow the GRACE mission, which was launched March 17, 2002. Expected launch in 2017

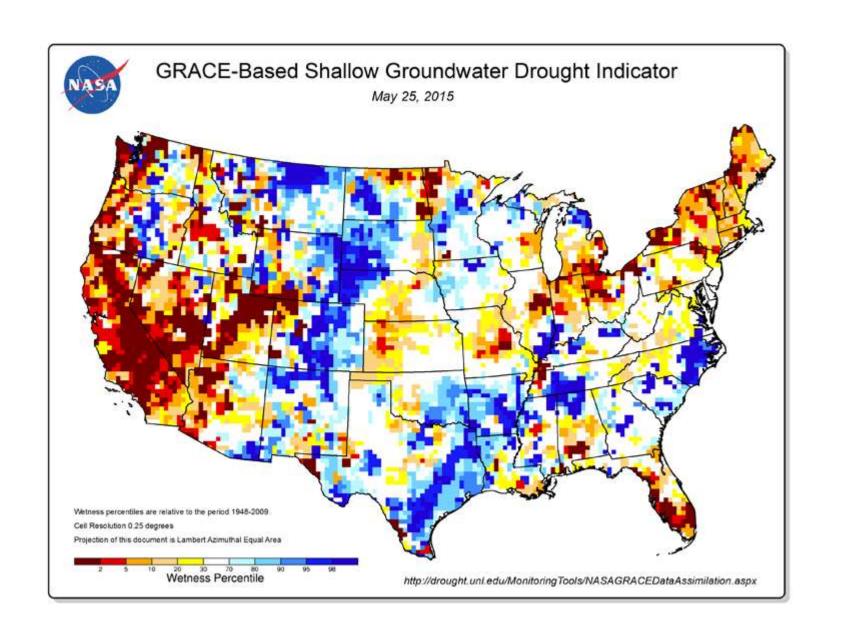
Scientific Instrument(s)

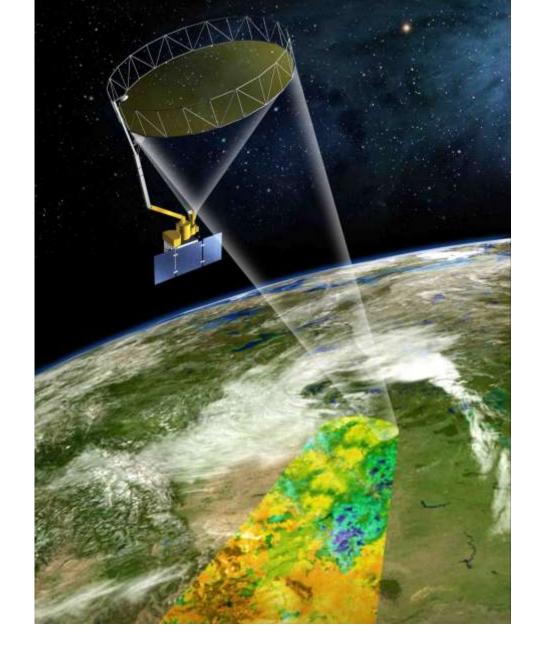
- Microwave K-band ranging instrument
- Accelerometers
- Global Positioning System receivers

The GRACE missions measure variations in gravity over Earth's surface, producing a new map of the gravity field every 30 days. Thus, GRACE shows how the planet's gravity differs not only from one location to another, but also from one period of time to another.



Changes in groundwater cause this measurement to change.





SMAP Mission: Soil Moisture Active Passive

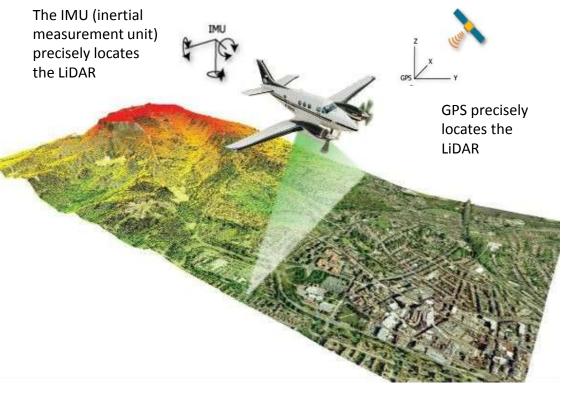
Launched: Jan. 31, 2015

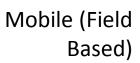
- provide global measurements of soil moisture and its freeze/thaw state.
- enhance understanding of processes that link the water, energy and carbon cycles.
- extend the capabilities of weather and climate prediction models.
- quantify net carbon flux in boreal landscapes
- improved flood prediction and drought monitoring capabilities

SMAP included a radiometer and a synthetic aperture radar (SAR) operating at L-band (1.20-1.41 GHz), with VV, HH, HV, at 1-3 km resolution; SAR failed soon after.

Sentinel 1's C-band radar is not the only radar in space — or even the closest substitute for the L-band radar — but it is the only one that trails SMAP closely enough to gather timely radar images of the swath of Earth that SMAP covers -

LiDAR instruments can be:

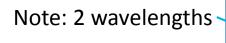


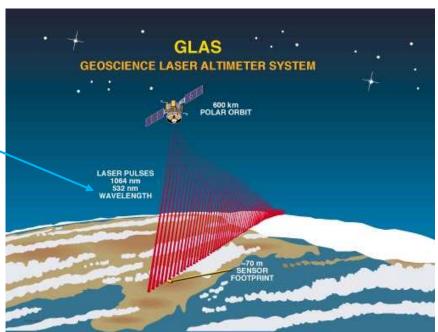




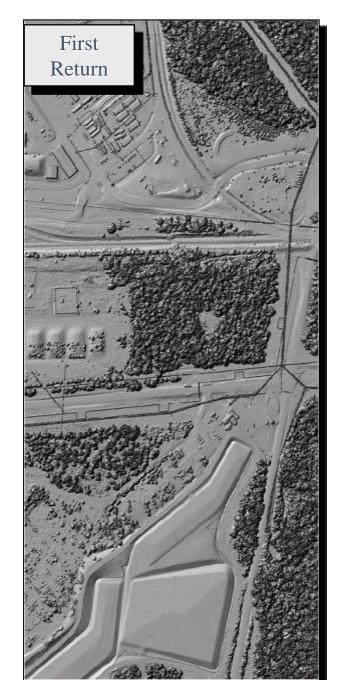


Mobile LiDAR Satellite LiDAR





Airborne LiDAR Data: Bare Earth Model







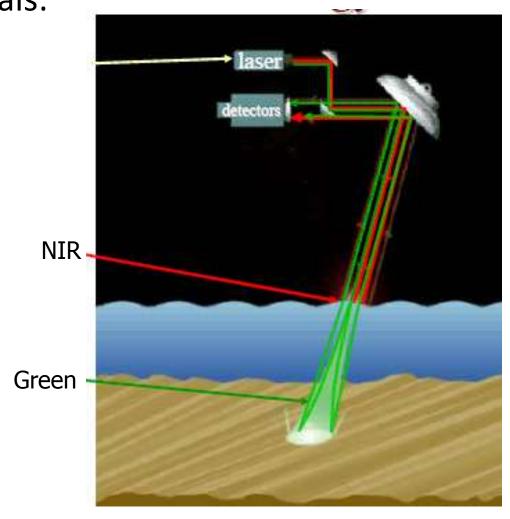
Bathymetry Measurements

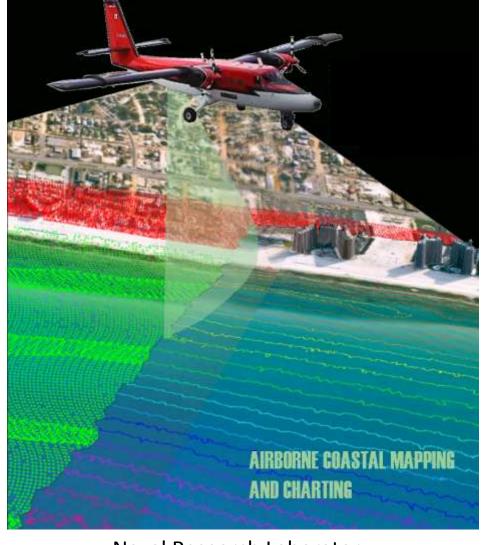
 Wavelengths (nm) used in USACE Shoals:

• 532

• 1047

• 1540



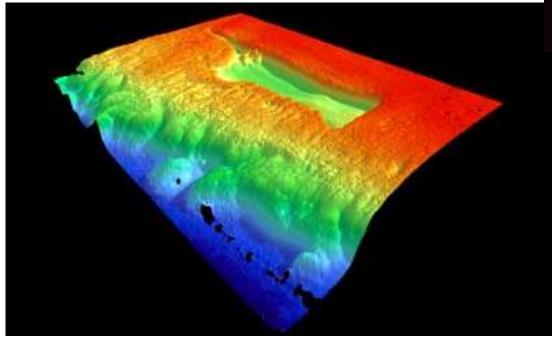


Naval Research Laboratory

D.Philpot, Cornell University, 2003 U.S. Army Corps of Engineers <shoals.sam.usace.army.mil>

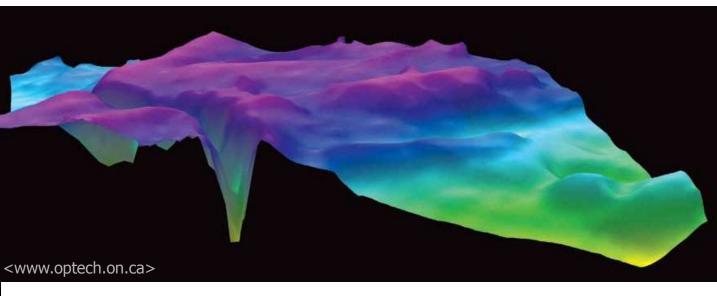
Near Shore Bathymetry

Looe Key, Florida



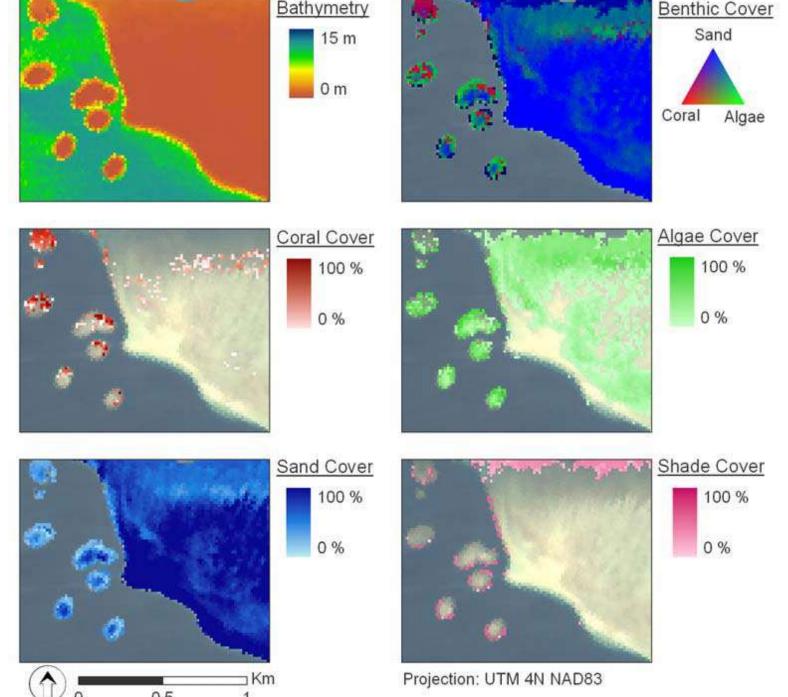
James Goodman

<coralreefs.wr.usgs.gov>



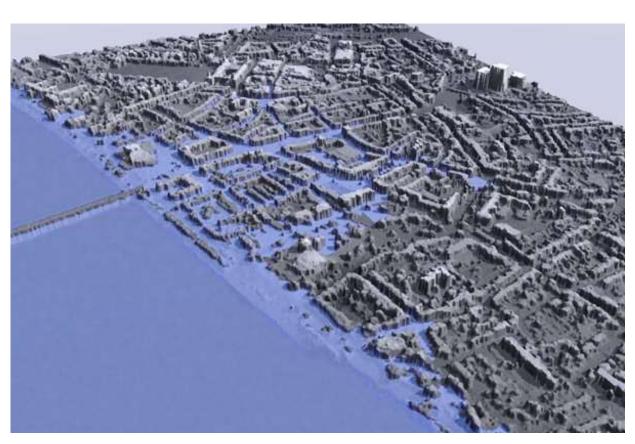
Molokai, Hawaii

Bathymetry (SHOALS) for a region with small corals of the coast of Kanehoe Bay, HI and classification of materials in area.

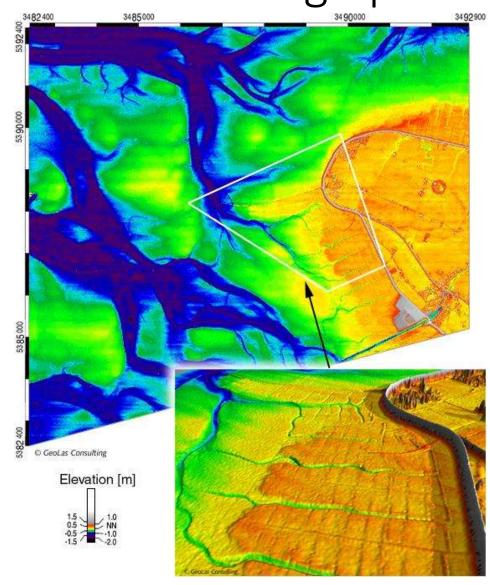


Goodman and Ustin 2007 Journal of Applied Remote Sensing, Vol. 1, 011501

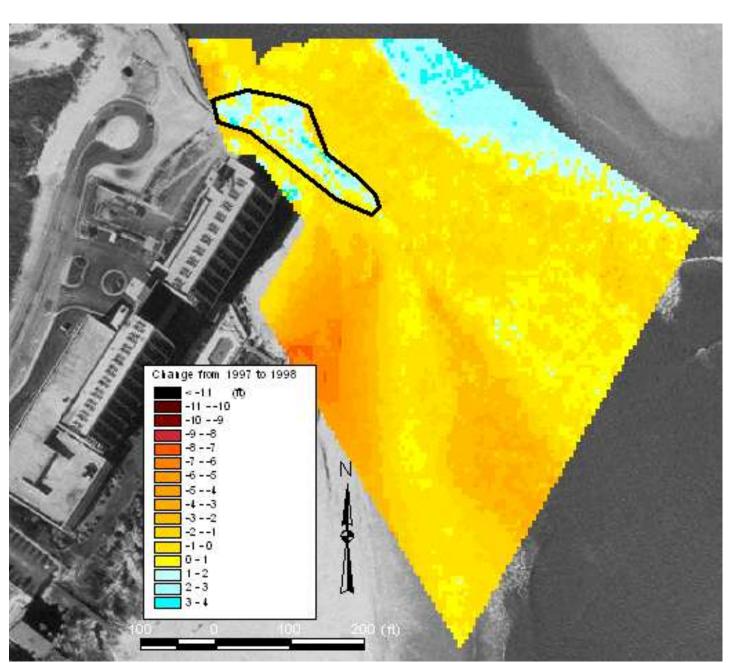
Floods: Water penetration into surrounding uplands



http://www.geolas.com/

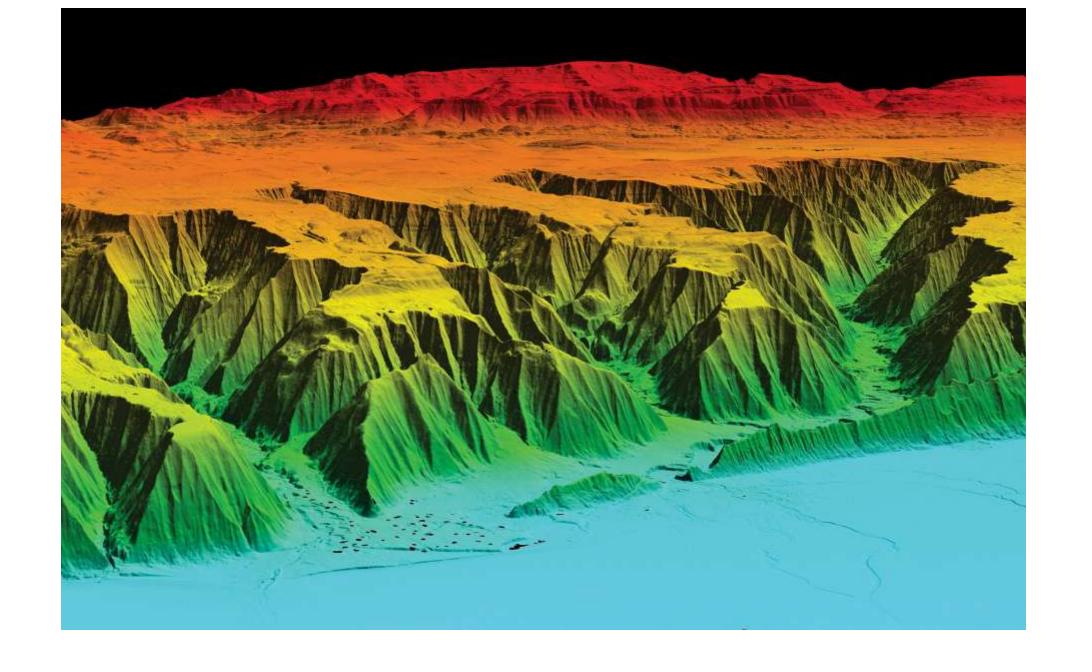


Coastal erosion



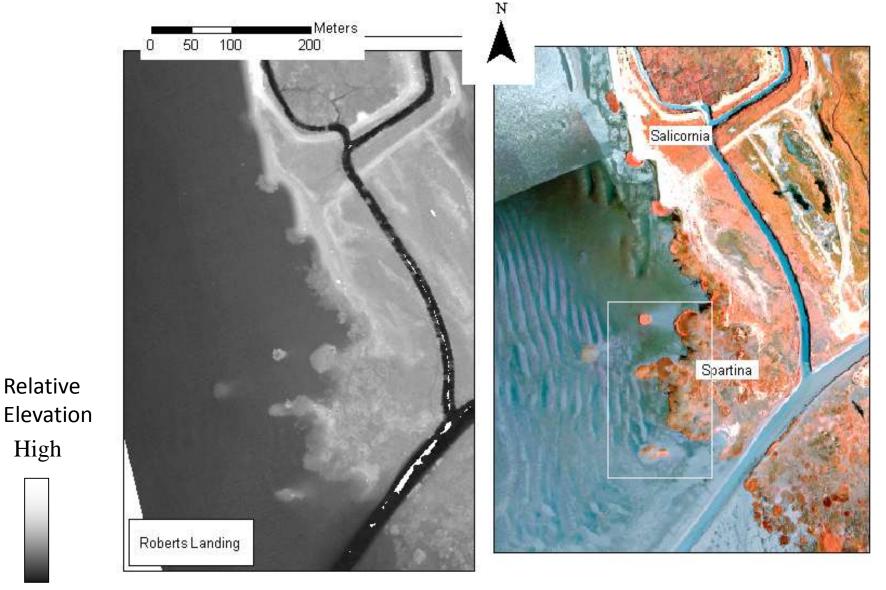
Mapping change in coastal elevation between 1997 and 1998 for coastal area of North Carolina (North Wrightsville Beach), on the southeast coast of the USA.

http://www.csc.noaa.gov/products/nchaz/htm/lidtopo.htm#lidar



Southern Kenai Peninsula, Alaska from LiDAR

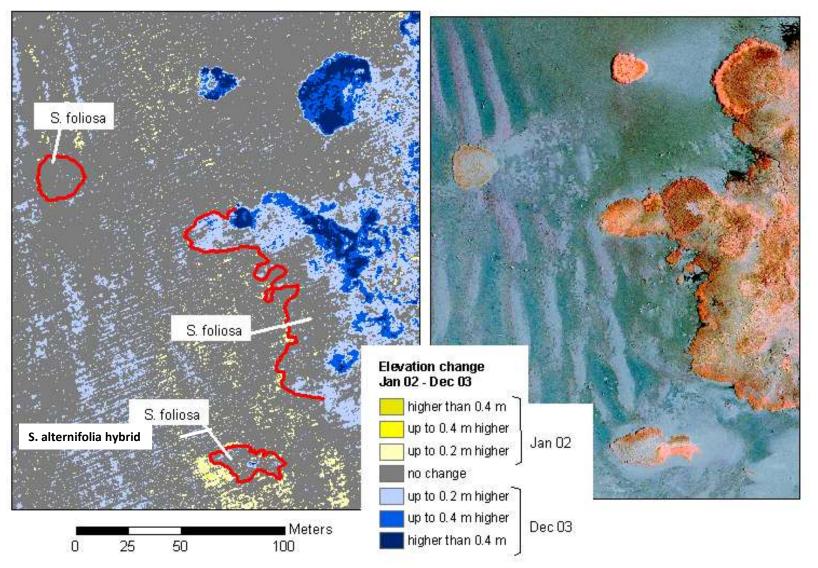
Expansion of Extent of Salt Marsh from Deposition



Rosso et al., 2006

Change Detection

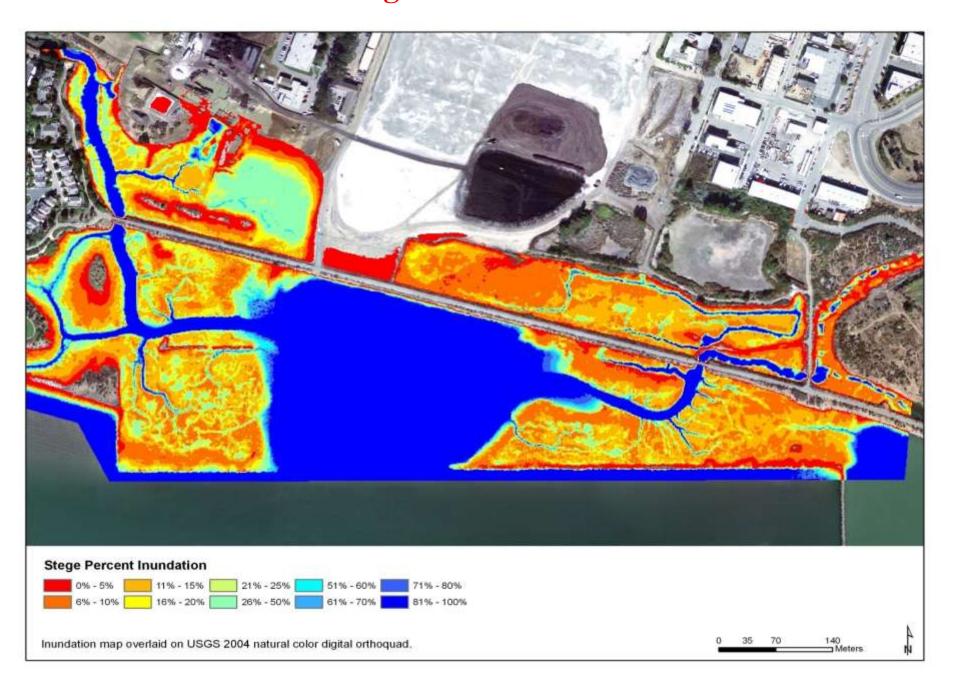
LiDAR Height Difference: January 2002 and December 2003



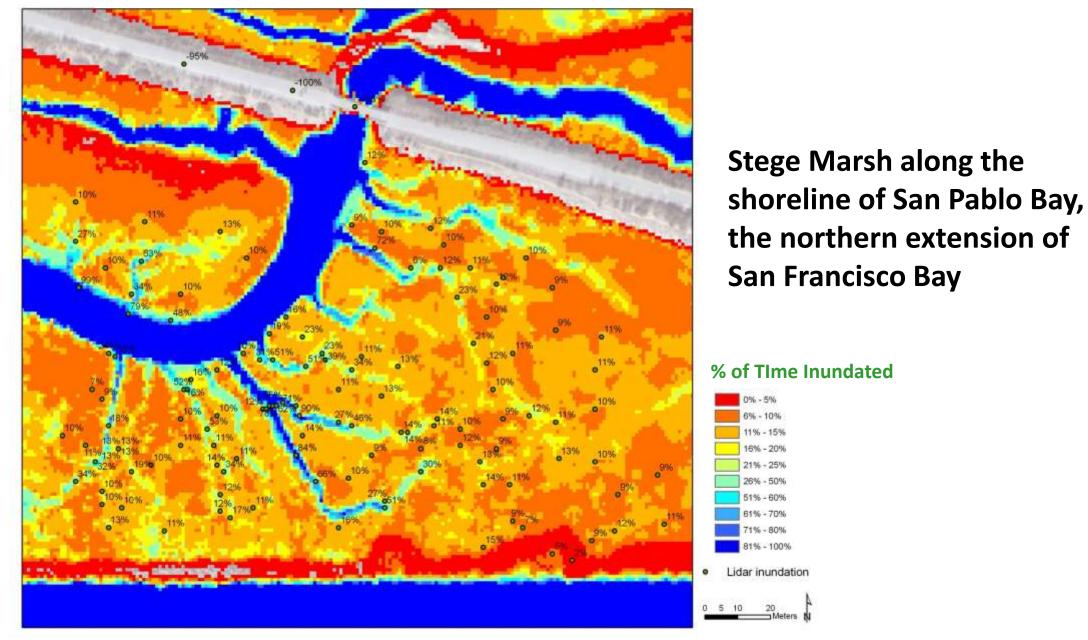
Roberts Landing marsh, San Francisco Bay

Rosso et al., International Journal Remote Sensing 2006

LiDAR Marsh Height: Estimate % Time Inundated



Micro-topography Controls Length of Inundation Period & Marsh Species Distribution





Sacramento – San Joaquin Delta

- Tidal estuary
- ~2500 km² area
- 1770 km waterways
- Aging earthen levees (built ~80-110 yrs ago)
- Subsidence (~7.6 cm/yr)
- ~2/3 of the population of California gets its drinking water from the delta

Levees:

- Protect farmland from inundation and erosion,
- Prevent saltwater intrusion into the freshwater rivers
- Control the rise of floodwaters during the rainy season

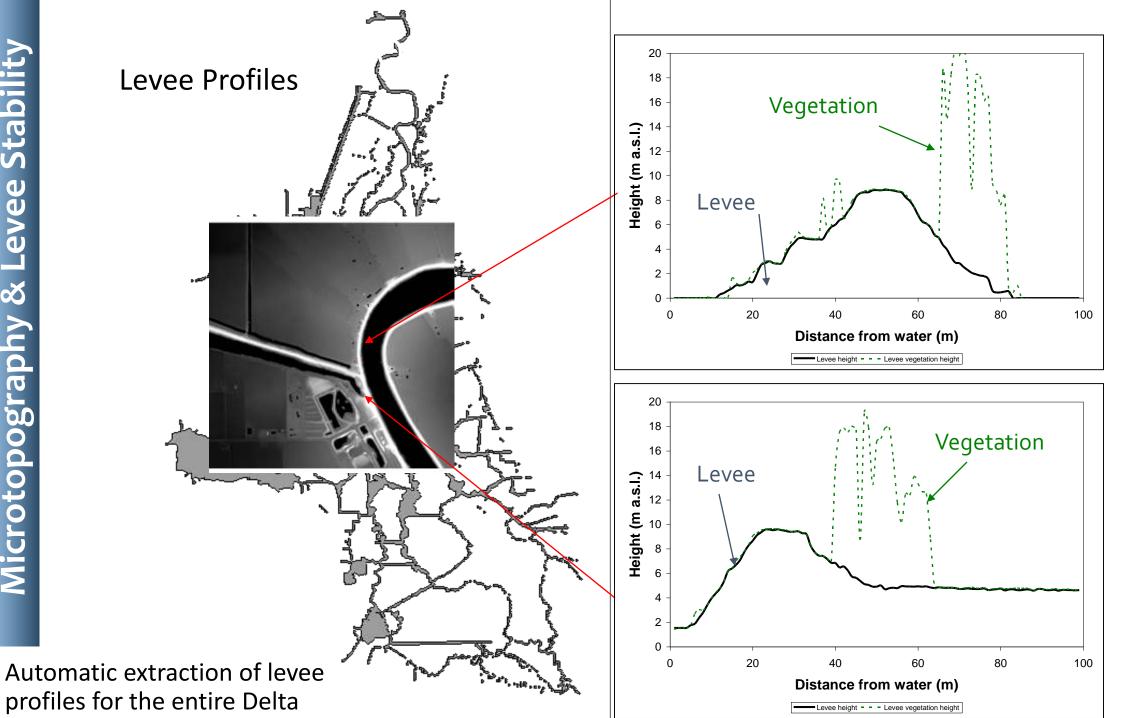
Levee's At Risk:

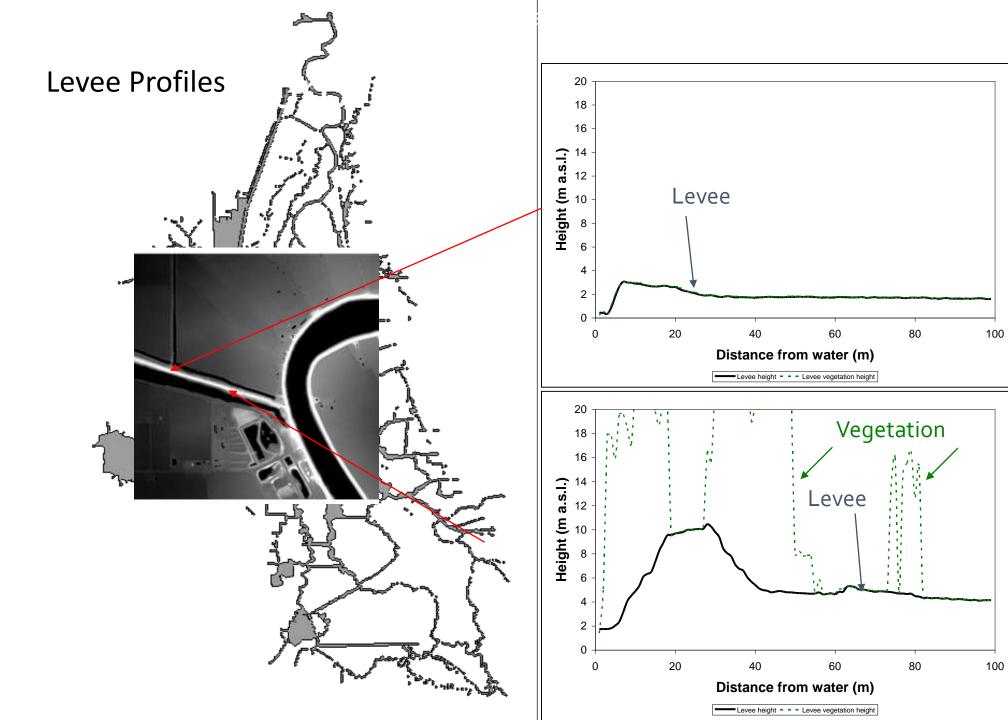
Poorly maintained Climate change Changing inflow Sea level rise Earthquakes

California's Sacramento-San Joaquin Delta is likely a next levee catastrophe, given its concentration of levees, people, and multiple potential failure



mechanisms (e.g. earthquakes, rapid snowmelt, winter storms, and poor maintenance. Flynn, S. 2007. The edge of disaster, Random House, New York.





Evaluate Levee Stability for Pocket Neighborhood of Sacramento

Sacramento Metropolitan Area



Quantify levee geometrics and its relation to vegetation occurrence and distribution over a 16 km reach of the Sacramento River using high resolution airborne LiDAR and Hyperspectral Imagery.





Pocket Area

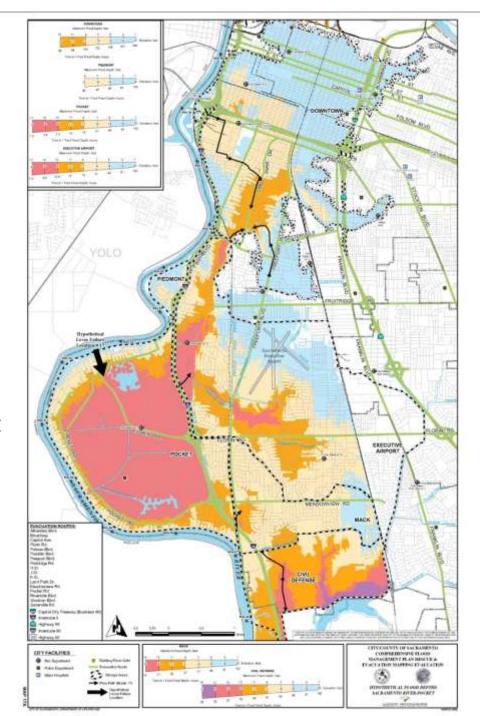
Why is Stability of the Levees in the Pocket Area Important?

Pocket Area, Sacramento

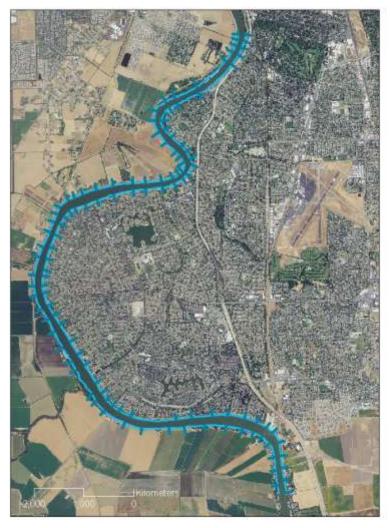
Maximum Flood Depth, Feet

| 7 | 15 | 13 | 11 | 9 | 7 | 5 | 3 | 1 |
| 6 | 8 | 10 | 12 | 14 | 16 | 18 | 20 | Elevation, Feet
| 3 | 3.8 | 7.5 | 13 | 19 | 31 | 44 | 81 | 192

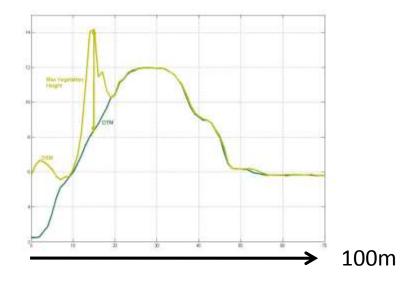
Time to Flood Depth, Hours



Methodology: Characterisation of levees against design standards using LiDAR data

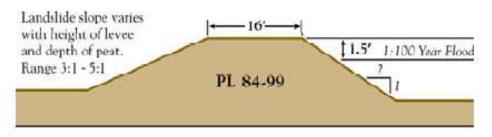


Profiles of the Terrain and the Canopy for 118 cross sections

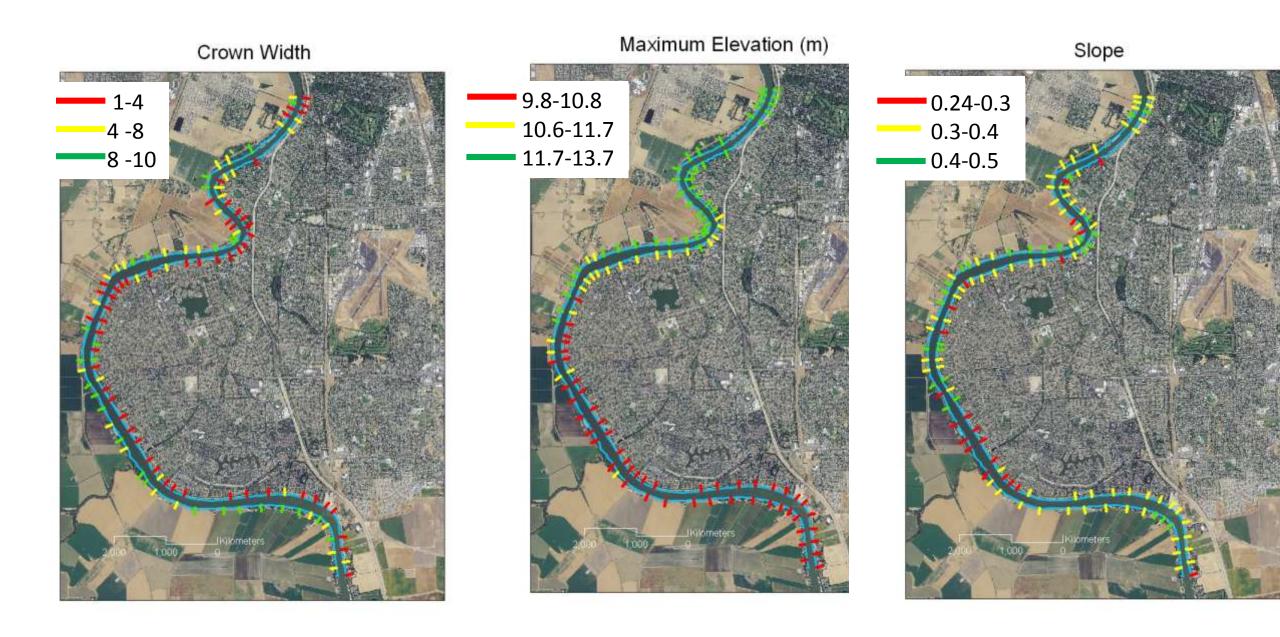


Delta Levee standards: crown width and slope

US Army Corps of Engineers (USACE)



Results: Stability Parameter Maps



Generalized Levee Stability Map

Sum of below standard conditions

Stability Level Definition:

Crown Width – Good > 4.5 m

Slope – Good > 45 %

Elevation – Good > 10.6 m

Stability level

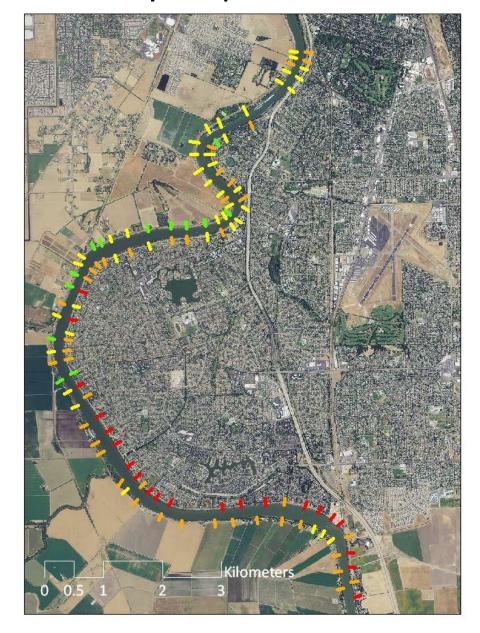
Good (0/3)

Fair (1/3)

Bad (2/3)

Unstable (3/3)

Stability Level	% of transects
Good	1.7 %
Fair	31.4 %
Bad	46.6 %
Instable	20.34 %



Lidar Images of Bare Earth and Canopy Topography

CAN MONT

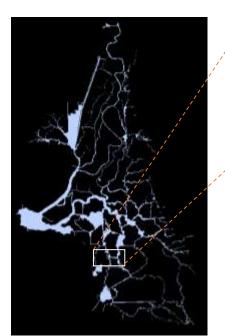






Objects > 2m above bare earth

LiDAR Improves Classification Performance





LiDAR – DEM 1st Return

Relative Elevation Highest

Lowest



Tree Crown Mapping

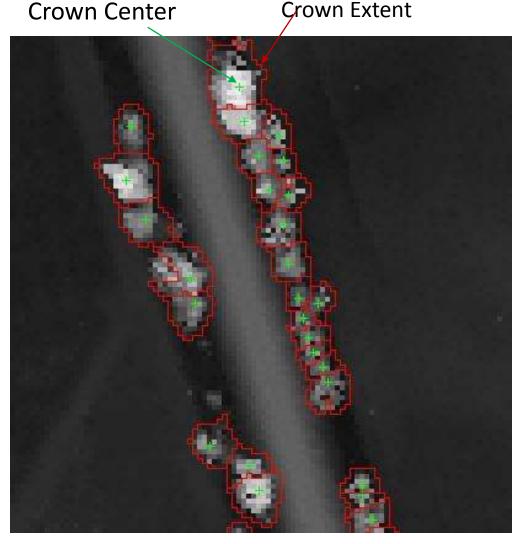


Fusing Lidar and Hyperspectral Data



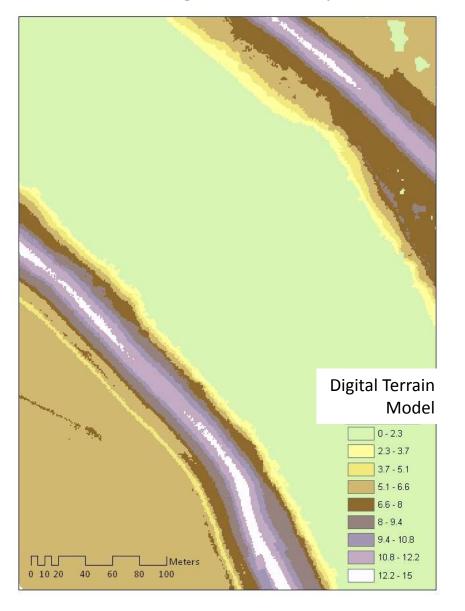
Tree Mapping Algorithm

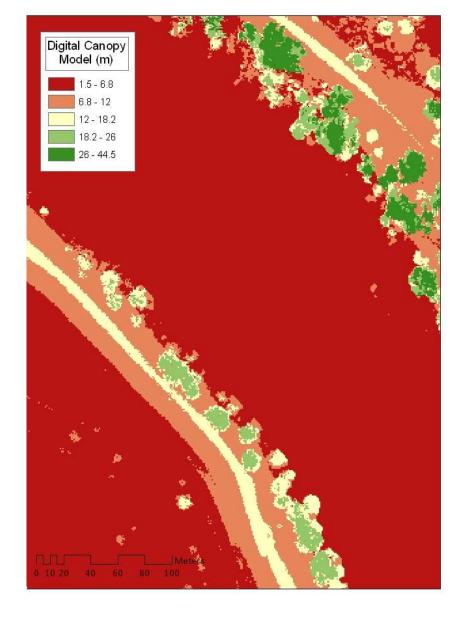
- Crown growing and valley following techniques are adapted.
- Segmentation based on elevation information from LIDAR height raster.
- Conic shape model for tree crown delineation.
- Spectral characteristics are involved to filter false positives from complicated background.



Juei Wren Ho

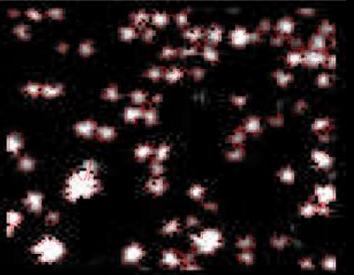
- (1) Assess levee stability by characterizing the superficial levee configuration using LiDAR data
- (2) Assess the role of vegetation as a possible instability factor using LiDAR data



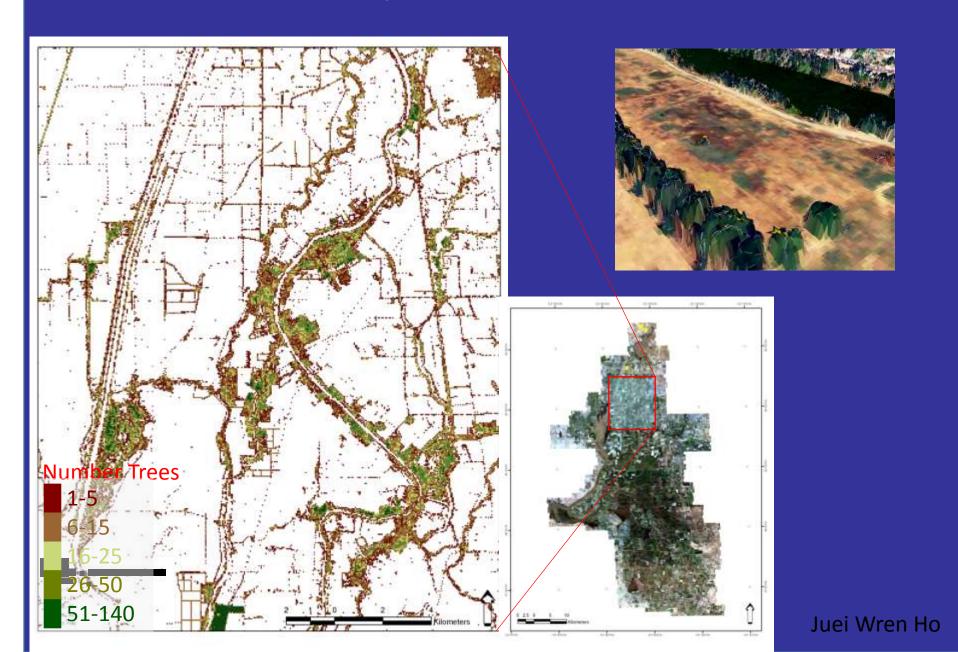








Delta Tree Map: 4,173047 tree "clusters"

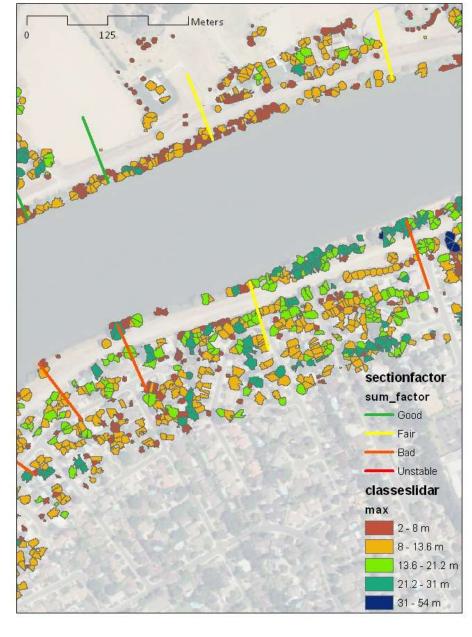


Relationship between tree structure and occurrence with the stability level of the levees

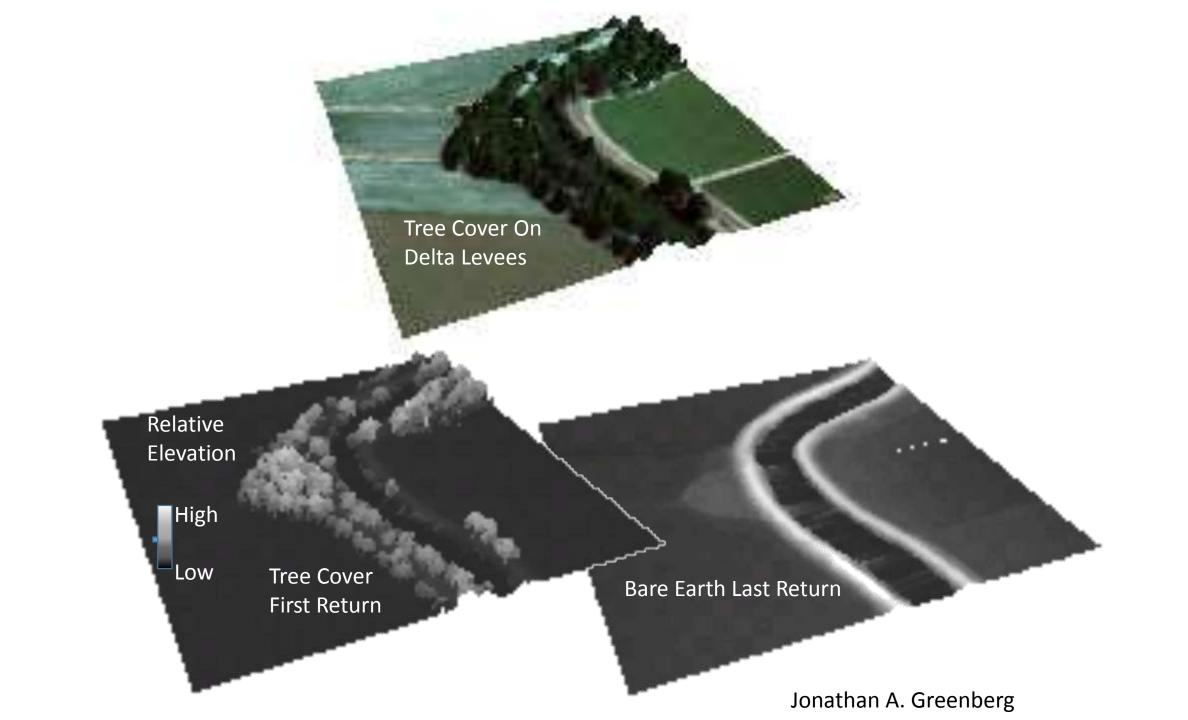
I) Vegetation Presence & Stability					
Stability Level	% of non-vegetated	% of vegetated			
Good	10%	0%			
Fair	5%	36.73%			
Bad	45%	47%			
Unstable	40%	16.32%			

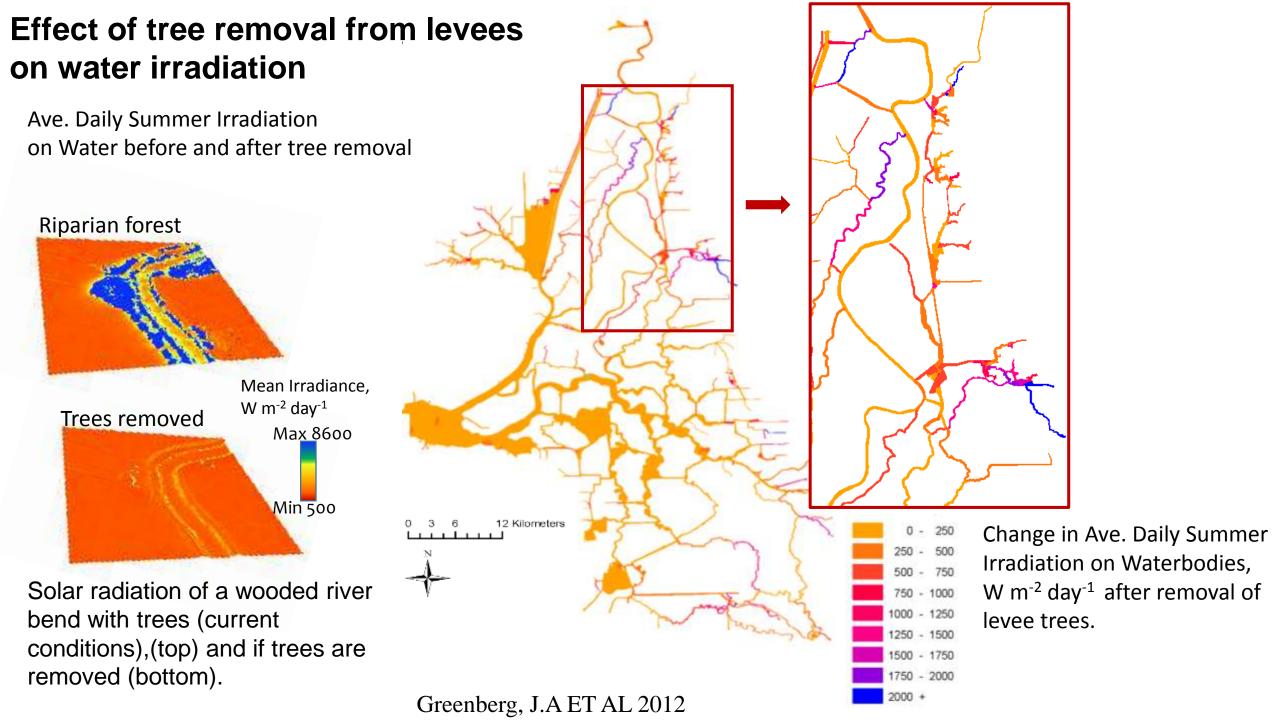
II) Maximum Vegetation Height & Stability					
Vegetated Levees					
Stability Level	Maximum vegetation height				
	[2-5 m]	[5 - 10 m]	[10 - 20 m]	[> 20 m]	
Good	0%	0%	0%	0%	
Fair	33.33%	43.48%	40%	28%	
Bad	46.67%	34.78%	45.71%	60%	
Unstable	20%	21.74%	14.29%	12%	

Maximum vegetation height (m)



^{*} Vegetation threshold >2m height





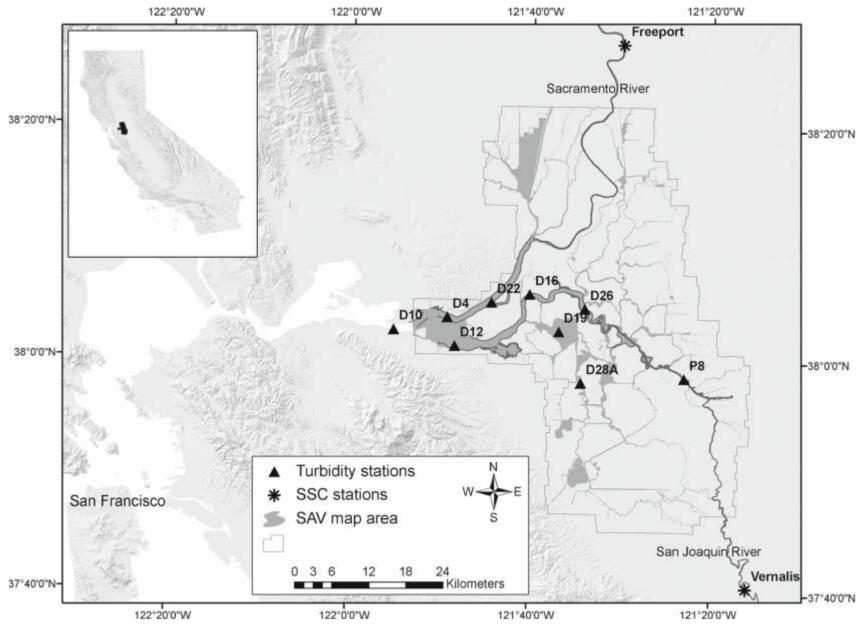
Aquatic plant communities of the Sacramento- San Joaquin Delta

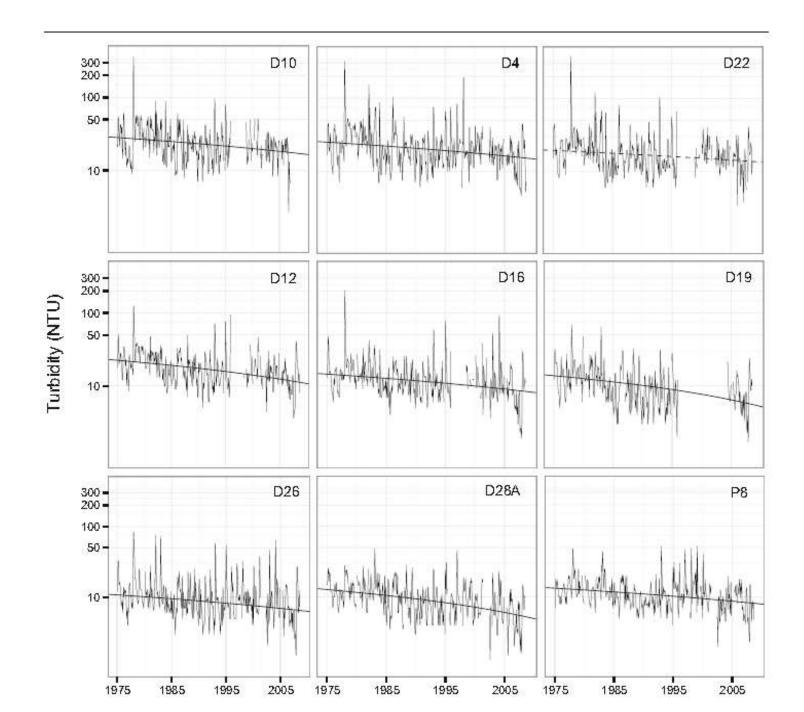


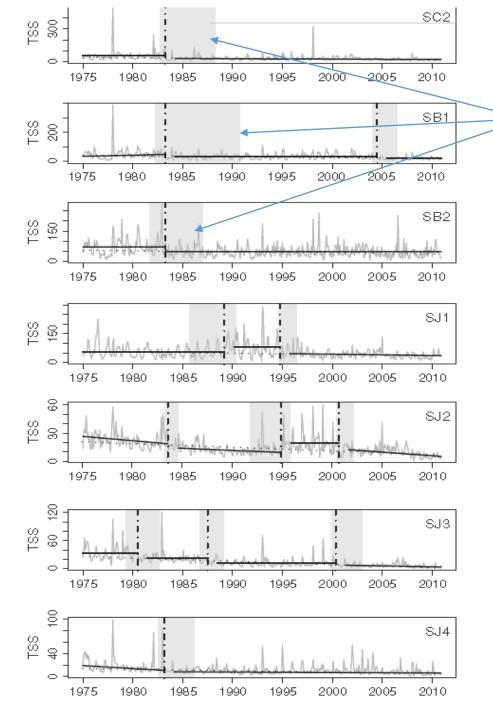


Turbidity in the Delta has been declining since the 1970s

- Dams on the Tributary Rivers
- Flushing of the last sediments from placer gold mining of the 1850s







Turbidity decline experienced 2-3 step changes:

After El Nino ~ 1985 (flushing event)

*Significant at 95% confidence

1990-2000 (rapid increase in SAV species)

