

#### Satellite radar altimetry: principles





Presented by

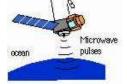
#### **Stefano Vignudelli**





With invaluable help (and material) from COASTALT, eSurge, C-TEP Projects and my colleagues and friends
Paolo Cipollini (NOCS, UK)
Ron Abileah (JomegaK US)



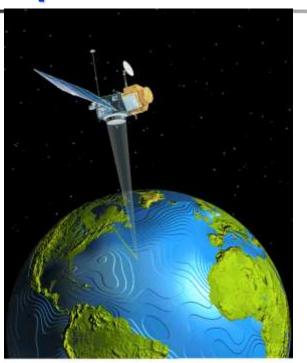


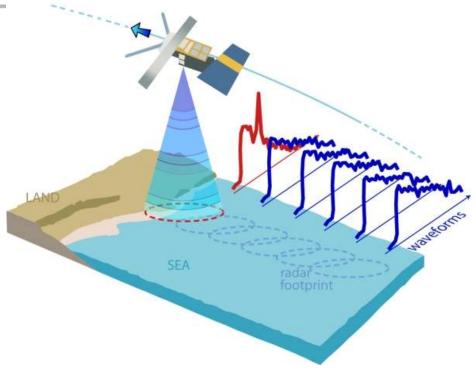
particular thanks also go to the Coastal Altimetry and Inland water Communities





# Satellite altimetry designed with the open ocean in mind



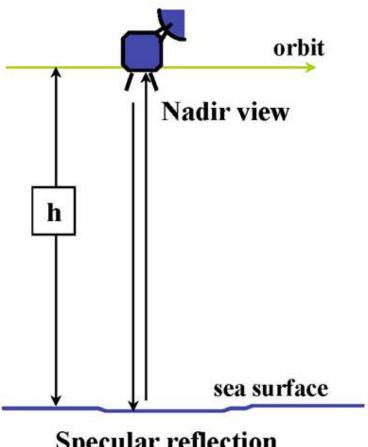


- Potential exploitation in challenging domains (coastal zone and inland waters) demonstrated in the last years
- The main problem is that measurements are taken near land/water interface
- No dedicated mission to inland waters until now; SWOT will be the first one but launch time is on 2020
- Satellite radar altimetry community is still limited in developing and exploiting satellite altimetry over the land



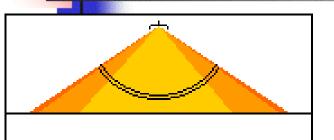
### **Basics of pulse-limited Altimeter** theory (I)

- Measuring travel time, **2T**, from emit to return
- **h=Txc** (c=  $3x 10^8$  m/s)
- **Resolution to ~1cm** would need a pulse of  $3x10^{-10}s$  (0.3) nanoseconds)
- 0.3 ns would mean a bandwidth > 3 GHz that is very high radio frequency bandwidth
- The workaround is to use Frequency Modulation pulse compression

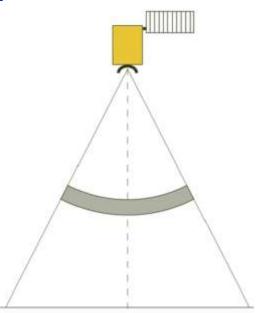


Specular reflection

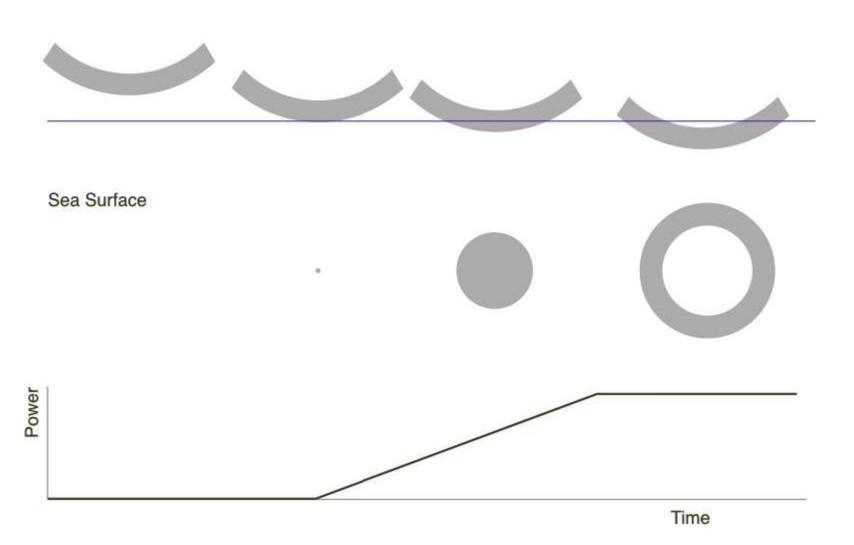
# **Basics of pulse-limited Altimeter** theory (II)



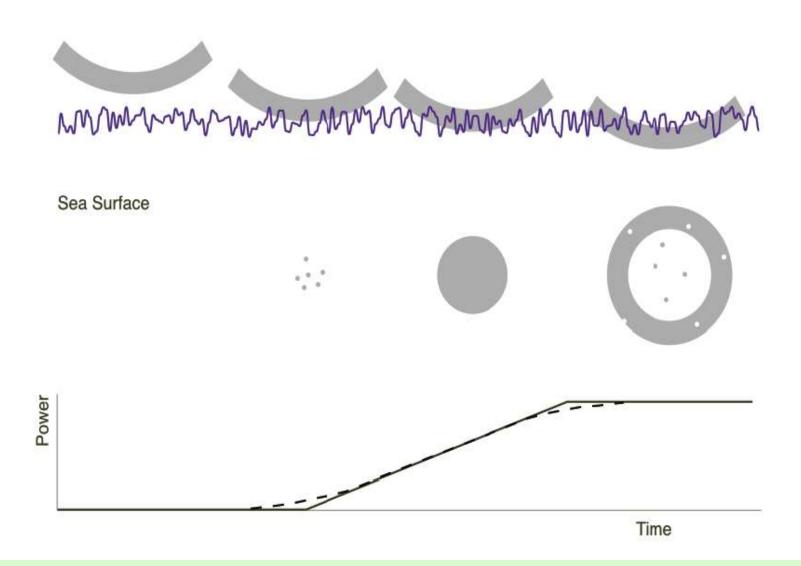
- We send out a thin shell of radar energy which is reflected back from the sea surface
- The power of the returned signal is detected by a number of gates (bins) each at slightly different energy
- In a pulse-limited altimeter the shape of the return is dictated by the width of the pulse



### This is what happens

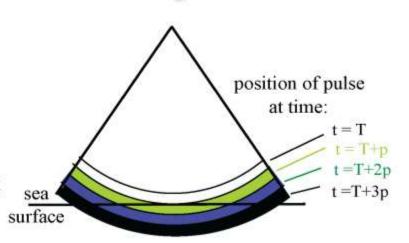


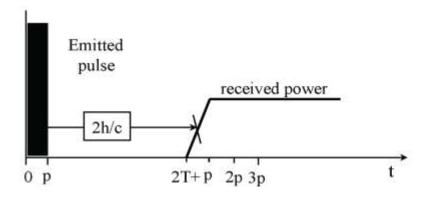
#### and if we add waves

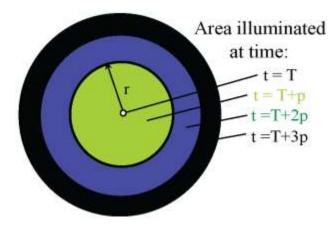


#### The Pulse Limited "footprint"

- Full illumination when rear of pulse reaches the sea – then area illuminated stays constant
- Area illuminated has radius  $r = \sqrt{(2hcp)}$
- Measure interval between mid-pulse emission and time to reach half full height

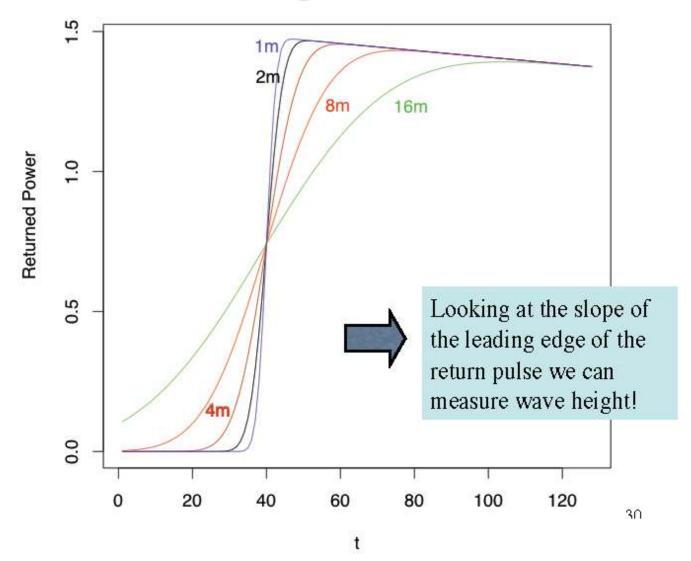






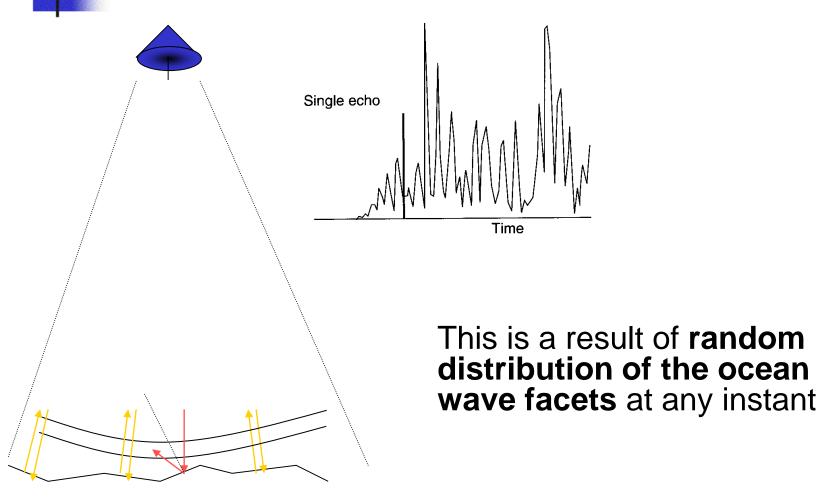


#### This is what we get at end

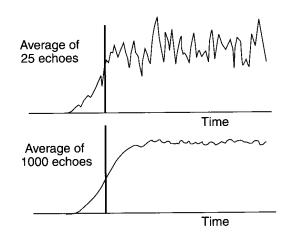


In big lakes we can have waves as they behave as oceans in miniature

### One single pulse collected over ocean is noisy



### Averaging many successive pulses can reduce noise



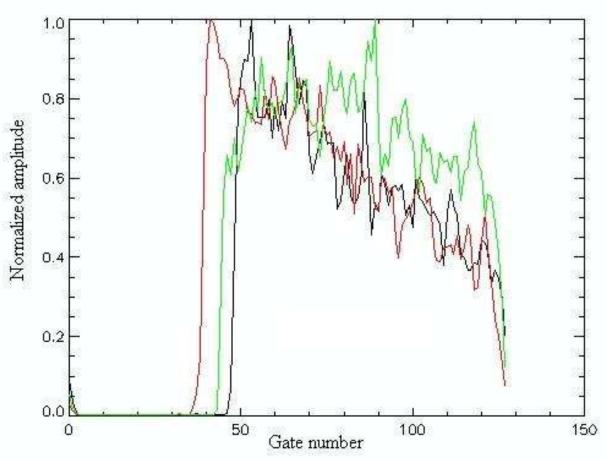
- We average (incoherently) consecutive pulses to achieve good Signal to Noise Ratio
- The pulse repetition frequency is thousands per second (e.g., 1020 for ERS-1/2, 1800 for Jason & Envisat, 4500 for TOPEX)
- Usually data are transmitted to the ground over 1/18 second of flight. This means measurements every 350 m along track
- However, data are furtherly averaged on ground over 1 second of flight, i.e. 7 km



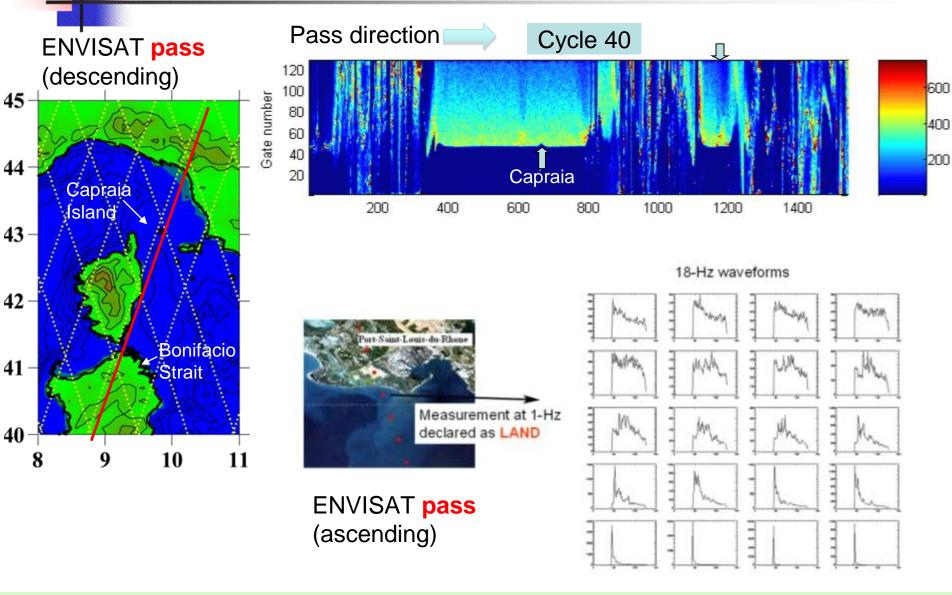
7 km is the nominal resolution in standard open ocean products

# Real radar return signals (waveforms) in open ocean and big lakes

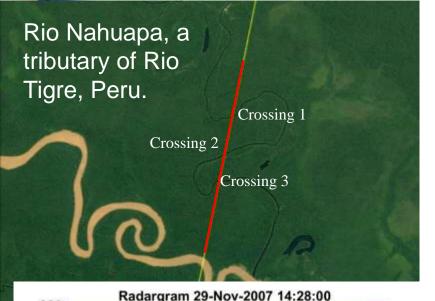


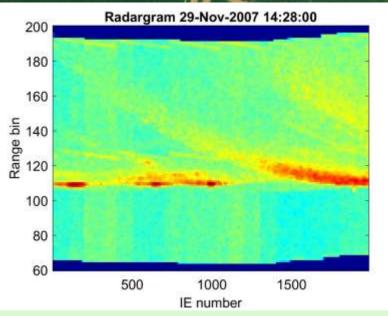


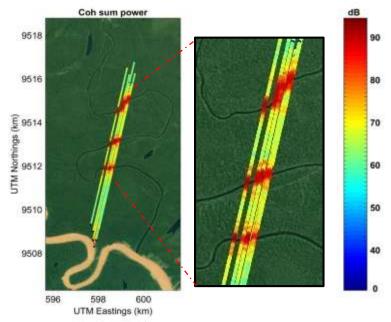
# This is to illustrate how complicated the radar signals get close land



### Here what happens when the satellite overflies small water targets

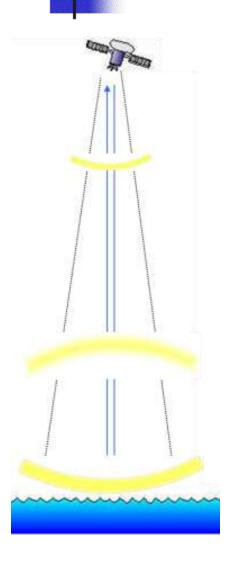


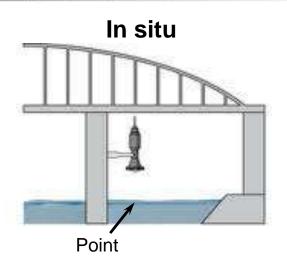




- Successive radar altimeter passes drift in longitude; interestingly, the effect of many passes over the area is to paint a map of the water surface
- The radargram has three striking flashes of specular returns corresponding to the three river crossings
  - The altimeter track never quite reaches Rio
    Tigre but some off-nadir returns from Rio Tigre
    are presumably seen at the far right

### The altimeter system is just a more complicated radar water gauge mounted on satellite

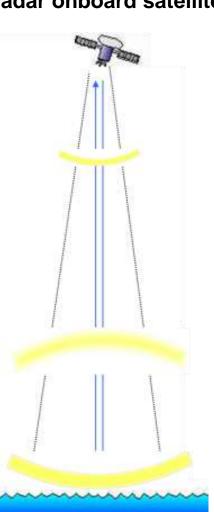


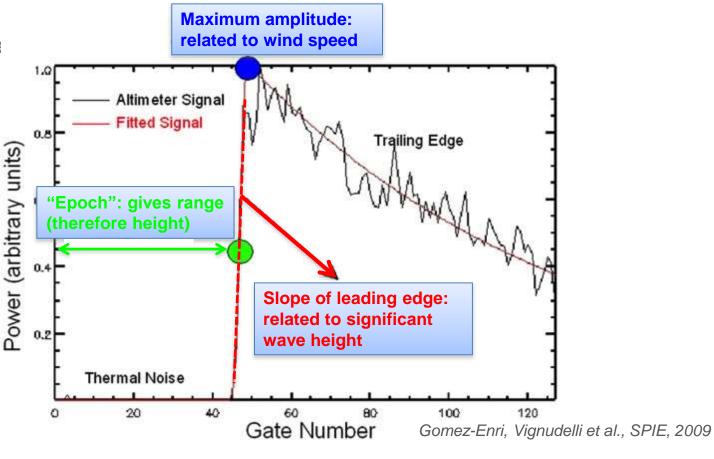


- Need of additional data (e.g. orbits and corrections)
- But more uses (waves, winds, currents, bathymetry in addition to water level)
- Averages over footprints vs point-wise
- Sampling of order of days vs min/hour

### How we turn 'return radar signal' into useful data



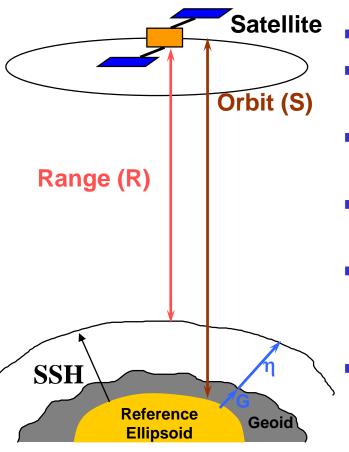




- Fitting the waveforms with a model (waveform retracking)
- That is how we estimate the so called range, wave height and wind from the waveforms

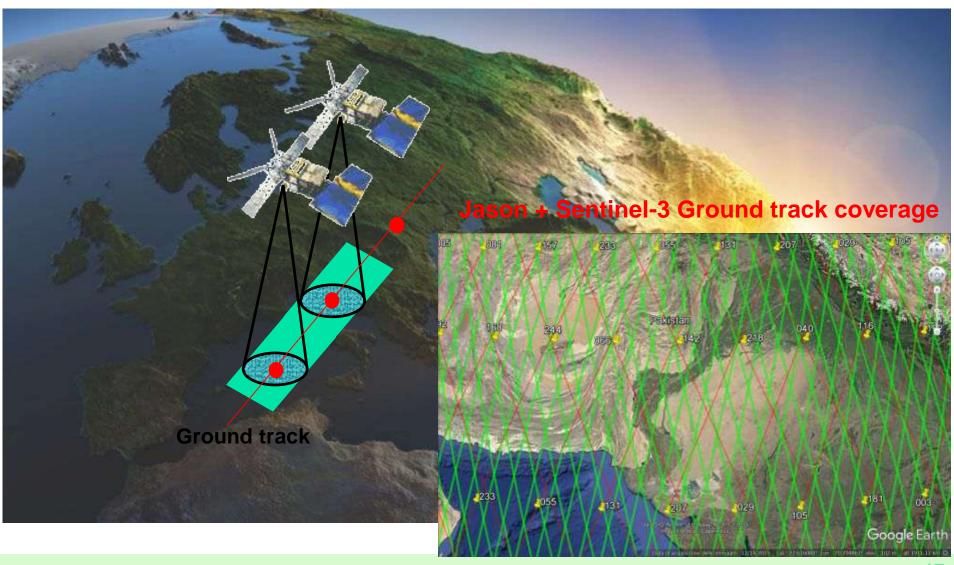
# How to transform range in usable quantities



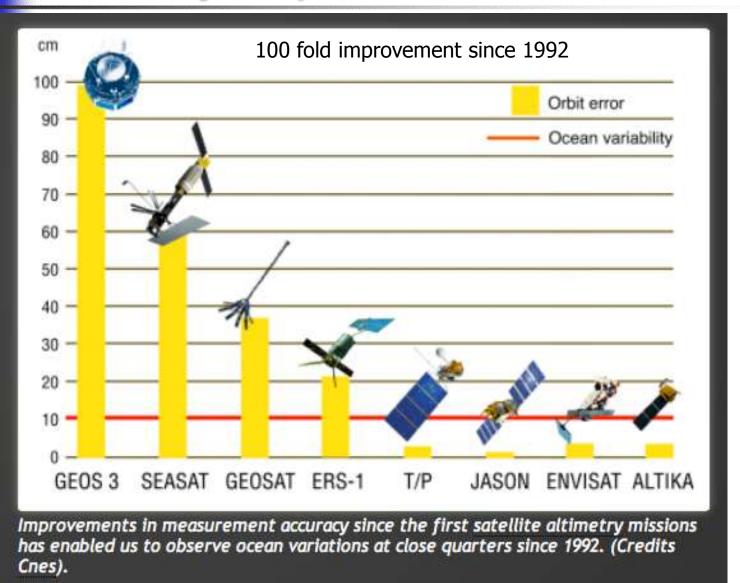


- Range (R) must be corrected for various effects (tropo, iono, SSB)
- We determine the position of satellite (S)
- Hence we compute the height of water surface (S-R)
- That height is usually referred to ellipsoid (called SSH)
- Ocean applications require to remove tides and wind/air pressure effects
- Auxiliary information (MSS, MDT) is then used to compute quantities used in oceanography (SLA and ADT)
  - In hydrology, the height of water surface (SSH) is usually referred to the geoid

# Remember: The current altimeters are not collecting pixels



# History of satellite altimetry accuracy in open ocean





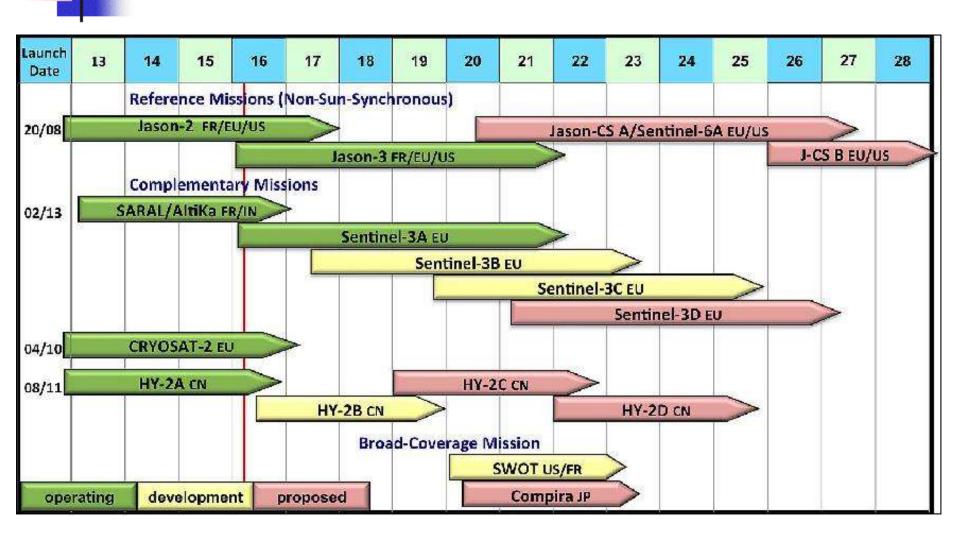
# Error budget for water level rivisited (in open ocean)

- Values in centimeters (1-sigma)
  - For average conditions (2 m wave height)
  - SAR reduces noise and overall SSH anomaly error

	Envisat	Sentinel-3	Jason-2	Jason-CS
Altimeter noise (LRM)	1.8	1.7	1.8	1.7
Altimeter noise (SAR)		1.3		0.8
Ionosphere	0.5	0.5	0.5	0.5
Sea state bias	2.0	2.0	2.0	2.0
Dry troposphere	0.7	0.7	0.7	0.7
Wet troposphere	1.4	1.4	1.0	1.0
Orbit error	1.9	1.9	1.0	1.0
SSHA error (LRM)	3.6	3.6	3.2	3.2
SSHA error (SAR)		3.5		2.8

Courtesy: Scharroo et al

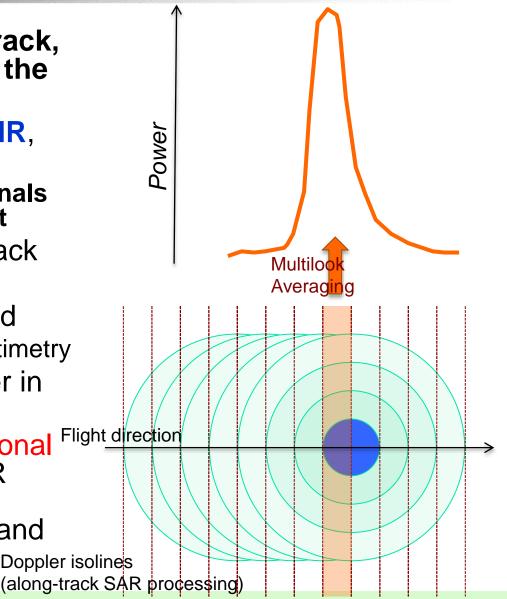
### Global Altimeter Missions: now and then



### Technical advances in challenging targets (coastal zone and inland waters): the SAR revolution

- We split the footprint along-track, and align multiple looks over the same resolution cell
- More "looks" means higher SNR, i.e. improved SSH accuracy
  - We can better detect small signals in "noisy" coastal environment
- Finer spatial resolution along track
  - ~ 300 meters along-track
- Less contamination close to land
  - So very well suited for coastal altimetry
- Cryosat-2 the first SAR altimeter in orbit
- Sentinel-3 now the first "operational Flight direction coastal altimetry mission" SAR mode over the whole ocean, including the world's coastline and inland waters"

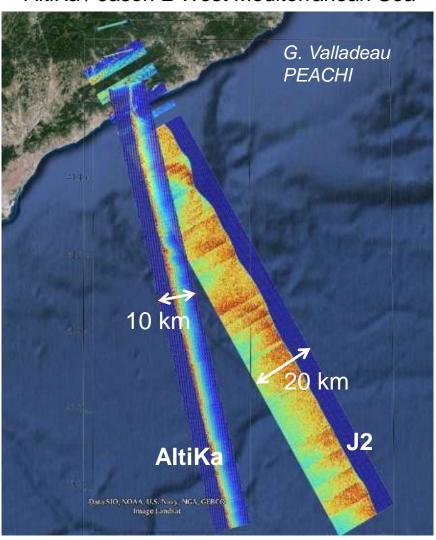
  Doppler isolines



### Technical advances at land/water interface: the AltiKa mission

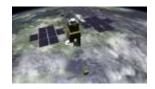
AltiKa / Jason-2 West Mediterranean Sea

- Smaller footprint than other missions
- Reduced range noise and SWH noise and finer spatial resolution (3db beam narrower than range gate limit) all promised a significant refinement of coastal altimetry (when matched by improved corrections)
- PEACHI project has introduced many improvements in processing
- AltiKa extremely good near land





#### **SWOT – A revolution**

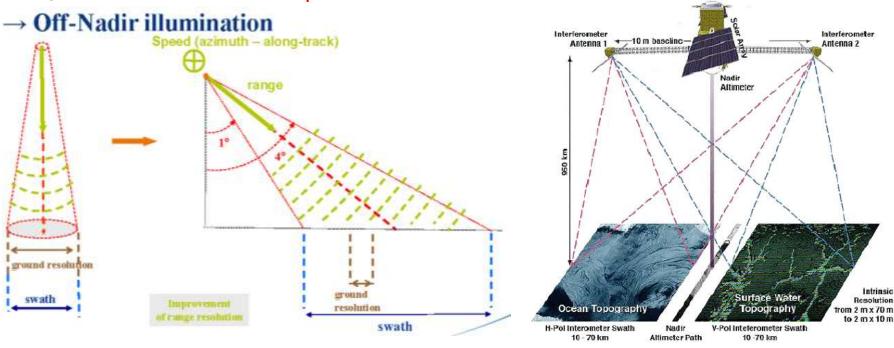


- SWOT means Surface Water & Ocean Topography
- Combining research needs associated to hydrology and oceanography
- From a fixed pattern (1D along track) to images (pixels)
- Mapping of water level for rivers, lakes, and oceans (including coasts)
- Principle: Wide-Swath Interferometric, Ka-band altimeter
- Expected launch date around 2020

http://swot.jpl.nasa.gov/

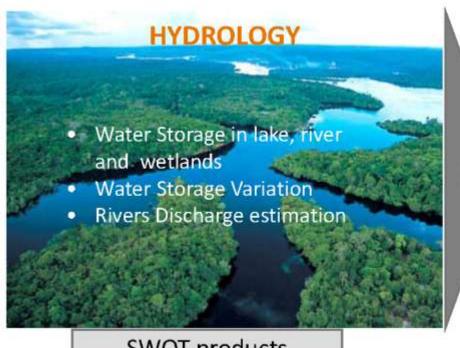
#### From nadir altimetry to SWOT





- It overcomes the main limitation of current altimetry (data collected along track only) using the interferometric technique
- It will provide a bi-dimentional image with an horizontal resolution of about 50-100 m.
- With its large swath, SWOT satellite will overfly water bodies at least twice every 21 days.
  - Potential of SWOT for transboundary surface water monitoring in International River Basins

# **SWOT** – the first altimeter mission for hydrology



**SWOT** products

- Transboundary rivers management (international & interregional)
- 2. A better modelling of flood
- Clear water management for urban, industrial and agricultural
- Hydroelectricity production management
- Prevention of the propagation of epidemics
- 6. Fluvial navigation support
- 7. Integrated management for estuaries

**Possible Applications** 

#### The inland water scenario



radar

Ground

Seoid

Geoid

echoes



- The actual radar altimeters collect data along fixed ground tracks. A critical limitation, even in a multi-mission configuration, is the coarse spacing (hundreds kilometers) between satellite orbital tracks, which means many water targets are missing from the observation
- Roughly **700 of the world's lakes** are crossed by the 35-day ERS/Envisat series, about **300** are crossed by the 10-day TOPEX/Poseidon Jason series
- Small water bodies have also proved tough targets for radar altimeters, because echoes deviate from the Brown shape

The present challenge is how to make the best use of the altimeter-derived water heights



# This is where satellite radar altimetry can contribute

- Water volume monitoring in lakes and reservoirs exploiting synergy with satellite imagery
- Bathymetry of water bodies
- Water discharge in rivers
- Water level in modelling, mapping and forecasting of flood events

#### Measurement of the water volume

- Radar altimetry used to measure the water level (L)
- Satellite imagery is used to measure the surface area
   (A)
- Abileah and Vignudelli further improved the technique with a water area algorithm and L-A fitting method
- The test case was Lake Nasser and artificial lakes it creates in the nearby Toshka basin
- Earlier results were also then validated with in situ water gauge data provided by Egyptian authorities
- The above research established a remote sensing based and consistent globally applied methodology to water area/volume measurement.
- This method can be applied everywhere



#### **Imaging satellites**

- Water area extent can be measured with a variety of space-based optical and SAR imaging sensors
- The different sensor systems and sensor modalities vary in revisit frequency, spatial resolution, and very significantly in cost
- Cost of imagery is a key consideration for L-A analysis due to the need for a time series of hundreds of images
- In this context the Landsat constellation is the best option as it provides images free
- Sentinel-2 constellation is now complementing Landsat and provides images free too

# Synthetic Aperture Radar (SAR) imagery (I)

- At low to moderate nadir angles the radar backscatter is very good at discriminating land and water
- Radar can 'see' day/night and through clouds which can be an important consideration the cloudiest regions
- According to NASA (http://isccp.giss.nasa.gov/) and Washington University cloud data bases (http://www.atmos.washington.edu/CloudMap/) worldwide daytime average cloudiness is 50-60%, but is geographically variable, from cloud 10% in Egypt to 70-80% at very high Northern latitudes
- SAR satellites can potentially revisit in, two days (much higher frequency than Landsat - especially in the cloudiest regions)
- Radar and optical systems can be considered complimentary
- Radar is suitable during the rainy season but is affected by wind and lack of vegetation context during the dry season.

# Synthetic Aperture Radar (SAR) imagery (I)

- The one big drawback is cost. One of the most accessible space-based SAR is the C-band RADARSAT-2, operational launched December, 2007. It must be specifically tasked to collect data in an area of interest. If one begins a data collection effort, the data required for an L-A fitting would be available in several years. A ballpark cost estimate: 100 images at 10-m pixel resolution, \$500,000.
- TerraSAR-X features 1, 3, and 18 m pixels and repeats up to two days and has been operational since 2007. There is an archive of historical images but that is not likely to provide enough images for L-A fitting. A new acquisition costs \$5000 per image (about the same as RADARSAT-2) providing 30 km x 50 km strips with 3 m resolution.
- The COSMO-SkyMed constellation, which began with the first launch in 2007, and several more later, is an X-band SAR. Their 30 km x 30 km stripmap products, 3 or 15 m pixel resolution would be the most useful for an L-A analysis. The 3-m resolution cost is about the same as above. The lower resolution cost is about half.
- Sentinel-1 (ESA) constellation is now providing SAR imagery free of charge

#### Visible and IR imagery

- The SAR advantage with regards to clouds is not that helpful. For the L-A method clouds are not detrimental, just a minor annoyance
- The approach can wait for suitable cloud free images to populate the L-A curve of a particular water body
- Usually there are several years, in some cases decades, of imagery data for this calibration
- Once the calibration is made, the water volume can be monitored with radar altimetry alone and radar altimetry is of course immune to clouds
- There are two related issues to using imaging satellites: which of the several commercial imaging systems are most suitable, and in the case of multi-spectral imaging, which spectral band(s) are best for water area discrimination.

Satellites useful for water area mapping

	Resolution	Revisit		
Sensor	(m)	(days)	Cost	Bands <sup>1</sup>
MODIS	500	1-2		36 spectral bands
LANDSAT	30	16	Imagery	B G R NIR SWIR
			is free	Thermal, Pan
SPOT	10/20	3	Archival data	B R G NIR
			available for sale	SWIR Pan
IKONOS	4	3		B G R NIR
WorldView 2		3	Tasking satellites	Coastal-blue
			for user's	B G Y R RE
			area of interest	NIR SWIR & Pan
			is expensive	

- The spatial resolution of IKONOS and WorldView-2 is ~1-4 m depending on which satellite and water algorithms are used
- It would be desirable for accurate water cover mapping, especially smaller water bodies
- WorldView-2 has eight spectral bands including SWIR which is especially useful for mapping water
- WorldView-2 also provide 11 bit dynamic range, vs. 8 bits from most other satellites.
- The three additional bits of radiance resolution can be very useful in the marine environment

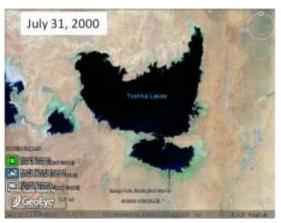


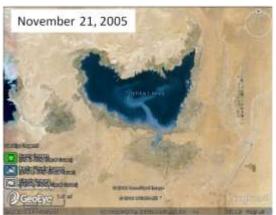
### High resolution imagery is expensive

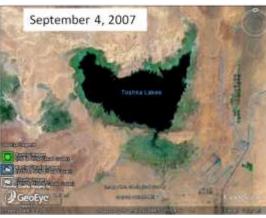
- The cost of the high resolution imagery is so prohibitive that they are unlikely to be used in the L-A analyses
- To illustrate this point, suppose a time series analysis is desired for a small catchments of 10 km x 10 km with 100 images. The image cost is about \$300,000. Also, as with SAR, there is unlikely to be archival data so a study of a particular water body would require the initiation of priority tasking (with extra cost) and results will not be available for several years

#### **Example of Toshka basin, Egypy**









Unfortunately these images are based on RGB colors, nice for visualizing the planet but the worst choices for landwater discrimination.

It is worth mentioning that the images from these satellites, or equivalent high resolution images, are easily and freely accessed with Google Earth. The images are limited to a few dates, typically ~5. The images are color composites, not the individual spectral bands. But some hydrological studies should be possible with such data, possibly in combination with radar altimetry time series.

lakes, Egypt, in four stages as seen in Google Earth snapshots. December 31, 1983 (before water fill), July 31, 2000 (near maximum), November 21, 2005, and September 4, 2007

Here you can see **Toshka basin** 

### **Example of Shasta reservoir California, USA**









Shasta reservoir, California, USA, in four fill levels as seen in Google Earth very high resolution snapshots, Clockwise from top left: June 11, 2005; November 7, 2006; July 27, 2009; April 24, 2010

## Landsat and MODIS (I)

- Eandsat and MODIS are the most practical choices for most applications
- Not only because the imagery is freely distributed, but also because of their long historical record (there is no equal)
- Landsat satellites have provided worldwide coverage since 1972 with a series of satellites
- In certain periods there were up to three Landsat satellites operating simultaneously (Landsat 4, 5, and 7)
- MODIS images are available from 1999 to present
- All the radar altimetry data is also free. So in the combination of altimetry satellites with MODIS or Landsat there is no data cost
- MODIS with 500 m resolution (in bands relevant to water area analysis) is most suitable for monitoring flood plains where the water cover can change in a matter of days. The relatively poor resolution of MODIS may be acceptable price to pay for daily revisits
- Landsat is better in cases where the water level change is slower, and resolution is more important in the tradeoff
- The pixel resolution of MODIS and Landsat can, for our purposes, be improved by a factor of 3-6, as will be discussed later

#### Landsat

- Landsat revisits at 16-day intervals, but this is only part of the revisit story
- In certain time periods there were multiple satellites in orbit and thus potential for more frequent revisits
- On the other hand there are areas of the world with months and even multiple years gap in imaging
- The revisits over the USA are at typically 16 days, but much less in other parts of the world
- On average there is a 50% loss of data due to clouds, with much geographical variability
- Another consideration is the hardware anomaly that occurred on Landsat 7 in May 2003 The imagery after that date has missing data stripes affecting 22% of the image area. Some Landsat users have managed workarounds to this problem.
- Given all the variables it is difficult to summarize the effective revisit rate in a simple way but one image every two month is typical.
- It is easy to navigate the Landsat portal (<a href="http://earthexplorer.usgs.gov/">http://earthexplorer.usgs.gov/</a>) to find images of interest Images may be available for instant download. More often images must be restored from archive. This may take a few days.



### Spectral bands (I)

- Landsat, like most other imaging satellites, is multispectral.
- The bands are Blue, Green, Red, near IR, and short wave IR, all with 30 m resolution
- There are one or two (depending on the satellite) thermal IR bands with 60 m resolution
- There is a panchromatic image with 15 m resolution.
- In principle all spectral bands can contribute towards land-water discrimination, but in practice only a few bands provide robust and substantial leverage on classification land-water.
- Blue and green have the least contrast due to a combination of low and variable land albedo and possible strong and variable reflection from below water substrate.

## Spectral bands (II)

- In turbid waters, the water spectrum shifts to red-near IR (Moore 1980)
- The degree of turbidity may be spatially variable, leading to variability in the near IR radiance
- This pushes our preferred discrimination band to the longer wavelength, i.e., the short wave IR, Landsat band 5 with response in 1.55 - 1.75
- If one desires one simple and robust approach to water detection, requiring a minimum of training and supervision, this is the band of choice
- The availability of 1.55 1.75 in Landsat is another of the several advantages of Landsat over other satellite systems for L-A analysis
- As an alternative to one band discrimination one may consider the water index (NIR-SWIR)/(NIR+SWIR), which combines the near IR and shortwave IR, as a pseudo one band input
- The higher resolution of panchromatic (15 m) would be also attractive for water mapping
- However the panchromatic spectral response spans blue to near IR, and does not extend to short wave IR so is not as robust land-water discriminator.
- The Landsat thermal IR bands (designated bands 61 and 62 in Landsat 7) are not considered due to the large pixels (60m), since our goal is accurate observations of smaller lakes and reservoirs.

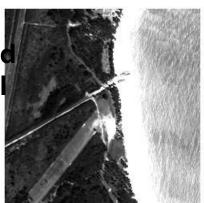
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### Spectral bands (III)



**Comparison of** shoreline and inland waterway in several spectral bands.



Green

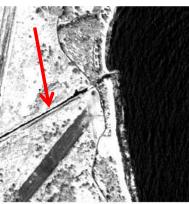
Strong bottom reflection is evident just offshore.

Yellow



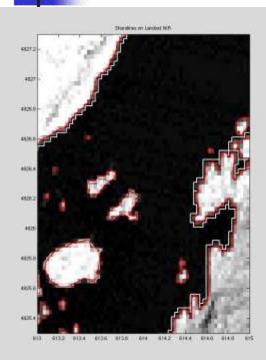
Figures show a stretch of the Oahu shoreline in Hawaii, imaged with the WorldView-2 satellite.

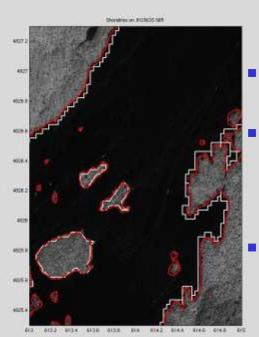
Short Wave IR



Note that an inland water channel is indistinguishable from the nearby airfield runway in blue and green. IR bands are generally better for water discrimination because there is a sharp increase in land albedo and increased absorption in water, leading to greater land-water contrast.

#### Water Area Algorithm





- The simplest and most often used land-water discrimination algorithm compares the IR to a preset threshold
- The darker pixels are classified water
- The water area is then defined by the outer boundaries of the water pixels
- The Landsat short wave IR band (or equivalent band in another satellite) is usually sufficient data for the method
- Figure shows an example with a section of Lake George, New York, USA
- The left panel is shoreline based on simple threshold (white) and spectral unmixing method (red) superimposed on Landsat IR image.
- The right panel is the same area in high resolution from Google Earth
- Lake George water level varies only <u>+</u>0.5 m in an annual cycle, so the comparison is useful even if Landsat and Google Earth images are from different dates.

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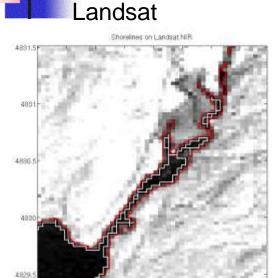
### Methods (I)

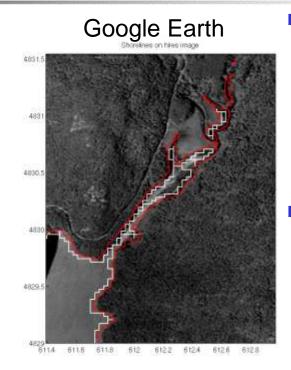
- It is evident that the white contour captures most of the water surface.
- It misses only water area that is within less than a pixel width from the shoreline because that 'last pixel' is contaminated with some land radiance
- A little land radiance in the mix makes the pixel indistinguishable from pure land pixels, at least when the discrimination is based only on pixel radiance level
- The omission of the 'last pixel' leads to an underestimate of the total water area. If the lake is large, this error is acceptable and nothing further is needed
- But for smaller water surfaces it is desirable to improve the resolution to capture more of the total water area
- There are two methods for improving the resolution:
   panchromatic sharpening and spectral unmixing

### Methods (II)

- IPanchromatic-sharpening combines 30-m MSI information with the 15-m panchromatic. Fox et al. (2002) tested four pan-sharpening methods on Landsat images in the vicinity of a small lake. The MTM, which was one of the four methods tried, appears to be as good as any method for water-land discrimination. It is also the simplest. The multi-spectral bands are up-sampled to 15-m and multiplied by the Panchromatic values. Then the multi-spectral images can be processed into water flags. But as noted earlier the panchromatic image is not always a robust water discriminator and it has no response in the short wave IR. For these reasons, we prefer the spectral unmixing, which also improves resolutions but does not use the Panchromatic image, and can be adapted to an optimum mix of spectral bands.
- The **spectral unmixing** method estimates the fraction of M pure material types present in each pixel. For example, we may estimate the relative amounts of water, vegetation, and sand (M=3), or water, trees, bare ground, and grass (M=4), etc. The simplest would be water and non-water (M=2). It is assumed that the total spectral radiance in a given pixel is a sum of the M types in different amounts. Since we are only interested in determining the water area, the desired shoreline are the pixels where the mixture is close to 0.5 water and 0.5 everything else.

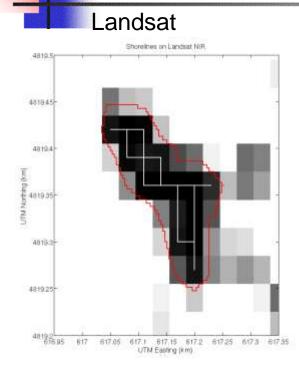
## **Spectral Unmixing (I)**

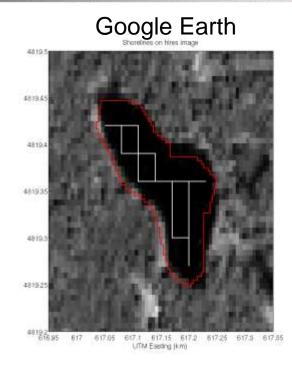




- This is a narrow water inlet attached to Lake George
- Simple threshold (white line) and spectral unmixing method (red line)
- In both images the ability to discriminate land from water is stressed with 30-m Landsat resolution and the simple threshold method misses a significant fraction of the water surface.

## **Spectral Unmixing (II)**





- This is a tiny unnamed lake at 43.518°N, 73.550°W
- Simple threshold (white line) and spectral unmixing method (red line)
- This very small lake is less than 100 m across the smaller axis
- The simple threshold identifies water in only a few pixels in the middle of the lake
- The unmixing process captures most of the water.



#### Our synergistic approach vs other studies

Other	papers
	pupe.s

Radar altimeters TOPEX + Envisat

Modis

Daily revisits

500 m resolution

Floodplains monitoring

(daily revisits desirable)

#### Our approach

Radar altimeters TOPEX + Envisat

Landsat
16-day
revisits
30 m
resolution

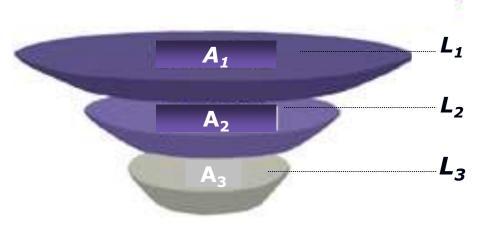
Reservoir volume
Bathymetry

(monthly revisits suffice)

- Some papers already introduced the idea of fusing radar altimetry and optical imaging satellites. In the same way, we combined TOPEX and Envisat radar altimeters into one time series of water surface elevations.
- The main distinction between the other papers and us is in the imaging satellite used. The others used the Modis satellite images with daily revisits and 500 m ground resolution.
- We used Landsat which has much better ground pixel resolution, but at expense of less frequent revisits. Landsat can revisit once every 16 days, but often less due to other operational constraints.
  - Our choice of satellites matches the application. For the other authors daily revisits are more important than resolution. For our application resolution is more useful than frequent revisits.

## Heron's Volume Method 10-70 A.D., Alexandria





$$\Delta V_{12} = \frac{|L_1 - L_2|}{3} (A_1 + A_2 + \sqrt{A_1 A_2})$$

$$\Delta V_{23} = \frac{|L_2 - L_3|}{3} (A_2 + A_3 + \sqrt{A_2 A_3})$$

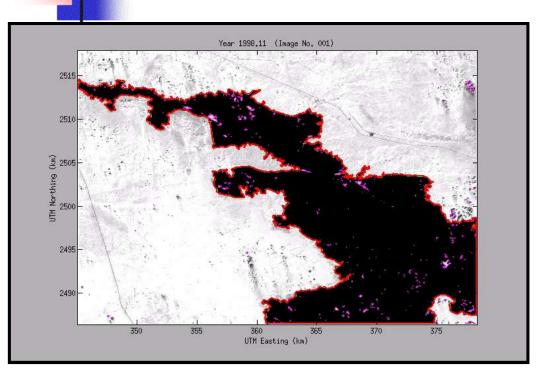
The basic idea in deriving the volume of a body of water is the same as first developed by Heron, a mathematician and citizen of ancient Alexandria.

As the water level rises and falls we measure the volume of slices of the water column.

Each slice is described by observations of area and level. Heron's formula gives the volume of each slice. Then we add all the slices.

We'll now show the modern, satellite based version of this idea.

#### **Landsat Temporal Image Series**



In this example, the water area used in Heron's equation is total area encompassed by [the red shoreline] minus [ total area of all the islands enclosed by the red shoreline].

This area is used in the following....

Shown here is the Landsat image of a section of Lake. We click to view movie of the temporal series.

The red line delineates the main shoreline. Pink outlines the shorelines of islands.

Many techniques exist, including commercial GIS software, to map water surfaces. We have our own customized Matlab algorithm that we think is an improvement of previous algorithms.

## How to fuse water level and area observations (I)

- The L-A function is found through fitting the temporal time series
   of area and water level
- However, since the two measurements are not co-aligned in time, one of the two time series needs to be interpolated to the times of the other.
- Radar altimetry data is more frequent than Landsat, typically 10 days
   vs. 2 months.
- Given this fact it is preferable to interpolate the radar altimetry data to the dates of Landsat imagery.
- Typical altimetry data is adequate for sampling of seasonal water level changes, as is common in lakes and reservoirs and can thus be safely interpolated. Interpolation is not appropriate in cases where there are diurnal tides, sudden floods, and similar short term variability.

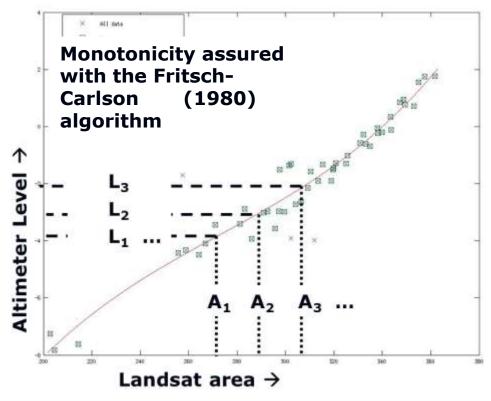
**50** 

## How to fuse water level and area observations (II)

- Some form of a least square fitting is used for a function relating the interpolated altimeter levels and Landsat water areas.
- Experience has shown that the conventional polynomial least squares fitting does not work well, either failing to capture all the inflection points in the data or oscillating wildly outside the data range.
- A much better fitting process is the SLMfit routine developed by John D'Errico (2009). SLMfit finds a set of connected cubic splines with various user specified physical constraints.
- In the L-A fitting the most useful is the monotonicity constraint of Fritsch and Carlson (1980).
- The slope range can be specified (MinSlope, MaxSlope in SLM language). Knot points (breakpoints) can be provided by the user or determined automatically to specify where there is a slope discontinuity and a need for fitting another spline.
- SLMfit also incorporates data weighting to desensitize the fit to data outliers. The process can be fully automated.

# I

#### **Polynomial Volume Method**

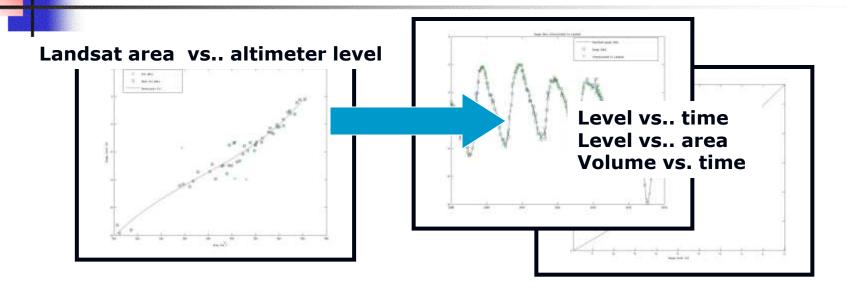


- Here individual observations of water area are plotted against the corresponding water level measured with a radar altimeter.
- X axis is area measured in Landsat images.
- Y is corresponding altimeter level.
- While there is a clear trend water area increases as the water level rises (obviously!)- there is some unphysical variability about the trend line.

#### **Error sources**

- The water levels deviate from a strict monotonically increasing relationship due to errors in the measurements and data reduction
- Further analysis (showed later) shows that most of the error comes from radar altimetry. So, the raw data can not be directly used in Heron's equation.
- The robust least-squares fit is used to parameterize the area-level relationship with a polynomial (with the fit constrained to be monotonically increasing) smoothes out the altimeter errors. This makes the data usable for volume estimation
- Error sources
  - Radar altimeter levels
  - Interpolation to Landsat dates
  - Water area
    - Image pixel resolution
    - Land-water classification
  - Level vs. area fitting

## **Analysis Products (I)**



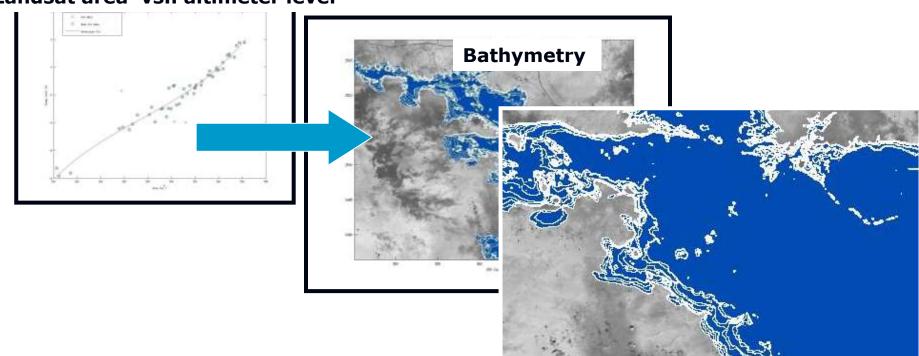
- Volume can be derived as a function of time, the water level, or the water area
  - Volume is relative to the minimum observed level
  - The volume below the minimum (down to dry lake) is not known

#### Smoothed water level time series

- Once the smooth Level-Area relationship is established future Landsat images can be used to derive the water level to very high accuracy
- Landsat images become very precise water level gauges.

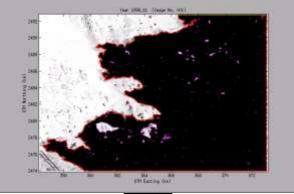
## **Analysis Products (II)**

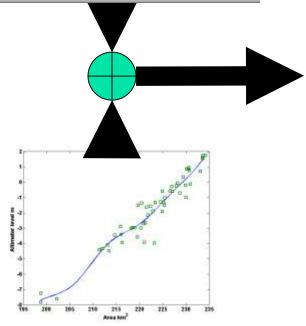
#### Landsat area vs.. altimeter level

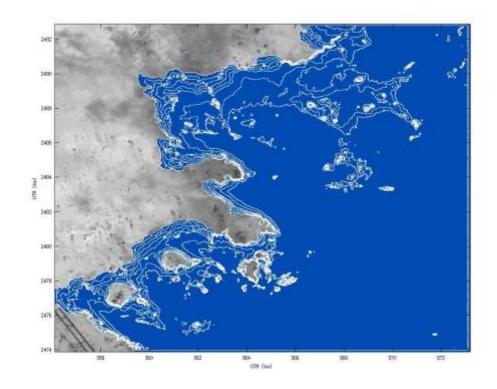


- Bathymetry, based on the shorelines outlined at various water levels
  - Here we show depth contours at 1 m intervals
  - In this method bathymetry is mapped over the range from highest to lowest water level experienced in the data
  - If observations extend from dry to full lake we can map the entire bathymetry

## **Bathymetry**

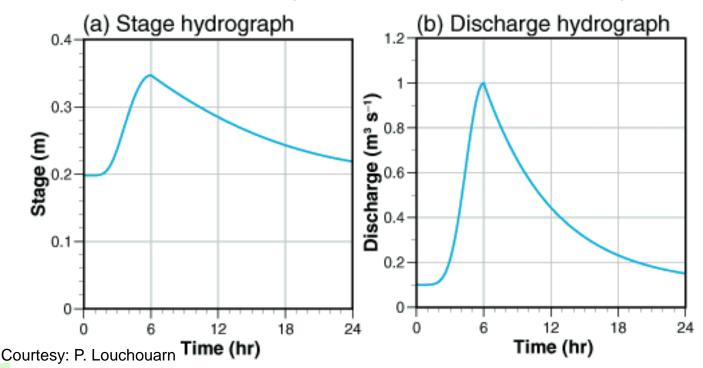






### River discharge and stage

- Fate of Precipitation -> runoff
- Rivers respond to precipitations
- Basic quantity to be dealt with is river discharge (as related to rain events) -> rate of volume transport of water (L3/t)
- What is river discharge and how do you measure it?
- Both river discharge and depth (so called stage) change with time.

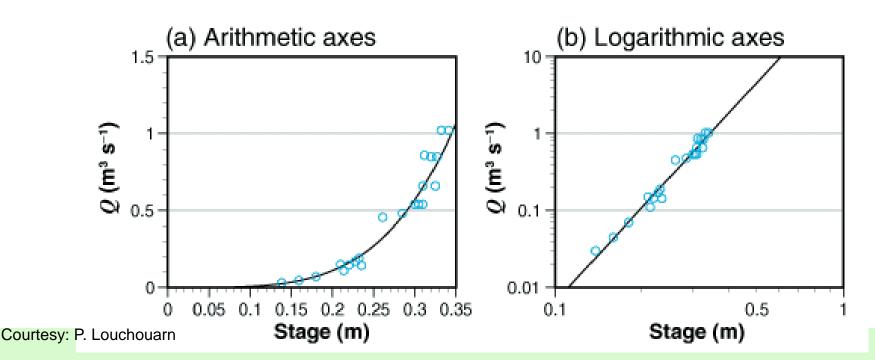


The term
"hydrograph"
refers to a graph
showing changes
in the discharge of
a river
over a period of
time. A hydrograph
represents how a
catchment
responds to rainfall

#### **Rating curves**

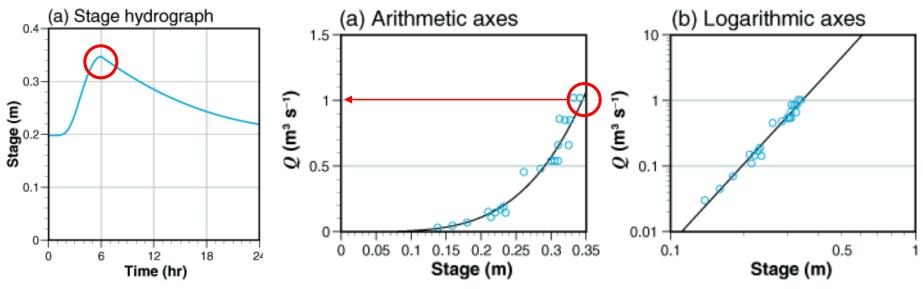
- Rating curve is a graph of discharge versus stage (height) for a given point on a stream
- Rating curve can be derived at gauging stations (measuring heights), where the stream discharge is measured across the stream channel with a flow meter
- The stage-discharge relationship will permit to derive river discharge using only stage measurements (assuming the relationship constant over time)
- Rating curves typically are nonlinear and often can be approximated using power functions:

$$Q = 76.5(stage)^{4.1}$$



## **Example**

- e.g. If stage peaks at 0.35m (at t = 6 hours), then the corresponding peak discharge is Q = 76.5(0.35)4.1 = 1.0 m3.s-1
- This way, a continuous measurement of river stage is used, in conjunction with established rating curve, to determine discharge as a function of time (almost all discharge hydrographs are determined this way)



Courtesy: P. Louchouarn

#### **Water Discharge**

- No remote sensing technique is currently capable of measuring directly river discharge
- Radar altimetry is the most promising technology to measure discharge from space
- Radar altimetry alone not useful
  - **low spatial** (80 km inter orbit spacing at the equator for ENVISAT) and 18 Hz data unsuitable for the monitoring of narrow rivers.
  - temporal resolution (between 10 and 35 days return period) longer than what is needed in particular for real-time optimization problems such as flood mitigation or reservoir operation.
  - do not coincide with in-situ gauges, so rating curves are not available (typically established by fitting a power-law through a number of points corresponding to simultaneous measurements of discharge and level)
- In order to overcome these limitations, many studies have focused on combining radar altimetry with other data or models.

### **Bibliography (I)**

- Kouraev et al. [2004]; Zakharova et al. [2006] Papa et al. [2010]
  - The authors use in situ measurements of discharge and altimeter-derived river heights at the nearby satellite crossing of the river (so called virtual station) to derive rating curves
  - The limitation of this method is that flow at any time can be estimated only where rating curves are derived, i.e., at virtual stations located near in situ gauges where the time coverage of the in situ and altimetric data sets overlap to derive rating curves
- Bjerklie et al. [2003]
  - The authors propose a method to develop rating curves based on the measurement of hydraulic data (water-surface width and maximum channel width) from satellite platforms in order to obtain discharge values at virtual stations not located near in situ gauges

## **Bibliography (II)**

#### Getirana et al. [2009] and Getirana and Peters-Lidard [2013]

- The authors develop rating curves based on altimeter-derived water heights and discharge estimated from a hydrological model and a routing scheme
- This methodology allows to obtain discharge estimates at the time and location of the satellite altimetry passages

#### Roux et al. [2008]

The authors propose a method to obtain daily time series of water heights from altimetry by exploiting neighboring in situ gauging stations, thereby densifying an existing level gauging network in order to obtain measurements with a higher temporal resolution than the satellite revisit time

#### Biancamaria et al. [2011]

The authors use linear regressions between upstream radar altimetry data over the Brahmaputra and Ganges and downstream gauged levels to improve water level predictions at locations not touched by the passages of the altimeters

### **Bibliography (III)**

- The main point is that many parameters in models are either not directly related to measurable quantities or need to be representative of large areas
- Therefore, hydrological models rely need a calibration/validation process where model parameters are tuned to fit simulated and observed states and fluxes.
- Calibration is generally made using in-situ discharge and levels
- The lack of such datasets for calibration can be a major obstacle in modeling of remote areas.
- Milzow et al. [2011]
  - The authors use altimetry in combination with other remote sensing data sources (surface soil moisture and gravity) to successfully calibrate a model of the poorly gauged Okavango catchment.
- Even when models are well calibrated, flow predictions are still subject to uncertainties due to errors in forcing data, model parameters and model formulation.
- For real-time applications, one solution is the use of data assimilation (i.e., the integration of observations into the model framework to reduce these uncertainties)

## **Bibliography (IV)**

#### Getirana [2010]

- The authors shows that radar altimetry from the ENVISAT satellite (35 days repeat cycle) could be used for automatic calibration of a hydrological model of the Branco river basin
- He find similar results to using in situ discharge data, provided knowledge of the rating curves at the virtual stations' locations

#### Refsgaard [1997]; Madsen and Skotner [2005]

- The authors show the assimilation of daily in situ flows or water levels to routing models
- The assimilation has been successfully been implemented in terms of remotely sensed river water levels

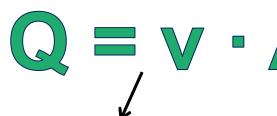
#### Neal et al. [2009]

 The authors show that hydrodynamic model predictions could be improved through the assimilation of water levels derived from combining synthetic aperture radar imagery and high-resolution digital elevation models (DEMs).



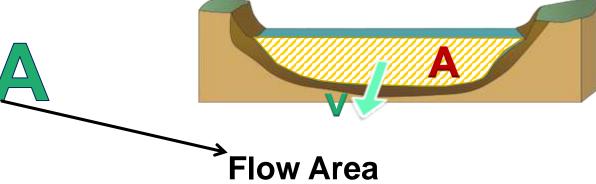
## Discharge estimated integrating optical and radar data





Flow velocity derived by MODIS

(Tarpanelli et al., 2013 -Remote Sensing of Environment)



A=f(water level, geometry)

derived by radar altimetry observation

Known (Topograp hic survey)

(Moramarco et al., 2013 – Journal of Hydrology)

unknown

#### Estimation of flow velocity (V) using sequence of images When water is present in a pixel or more water is added, its reflectance tends to decrease flood signal dry, wet wet M = water C = land pixel pixel (located (located near within the the river in an river with area free of surface water permanent C= Land pixel presence of even during

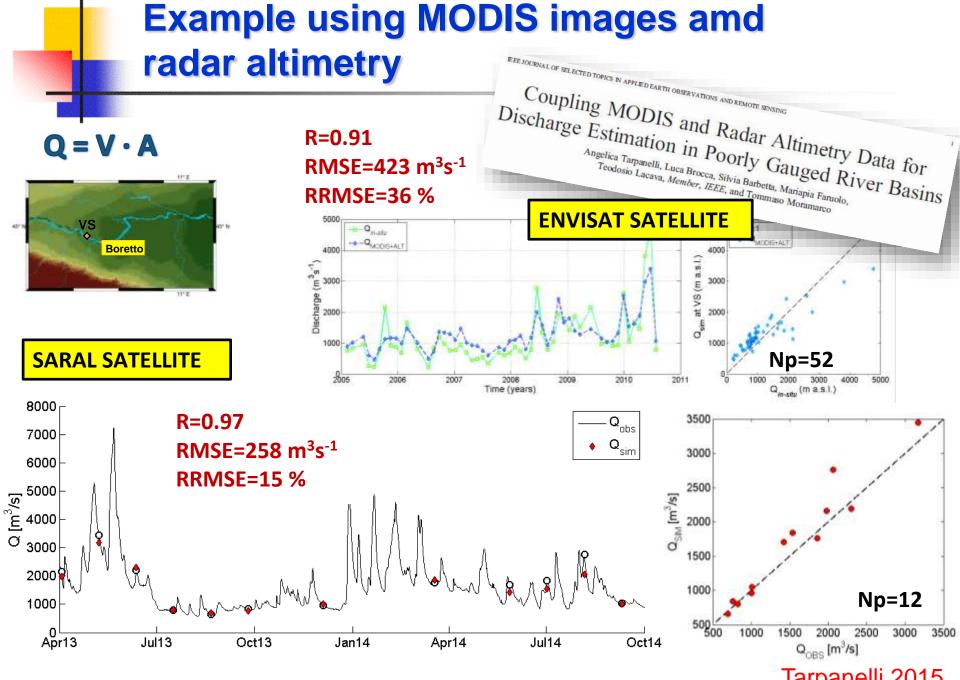
C/M increases with the presence of water and, hence, of discharge

high floods)

Brakenridge et al., 2005; 2007

M=Water pixel

water)

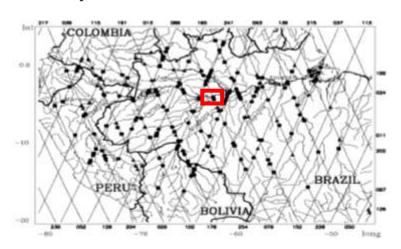


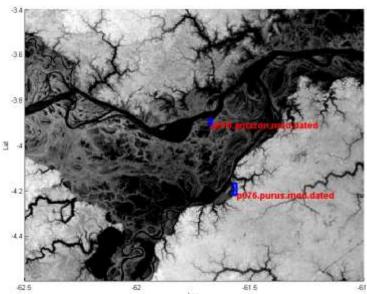
Tarpanelli 2015

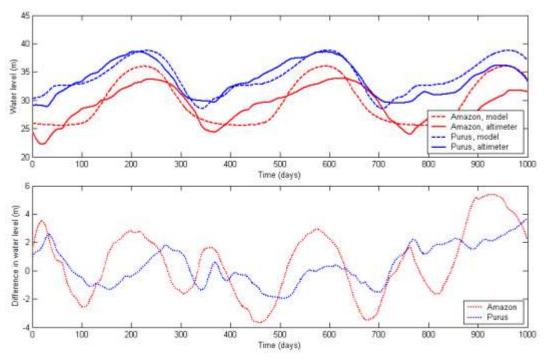
## Example of hydraulic modelling of floodplains (I)

- Flow on floodplains is controlled by topography and friction
- Leads to complex spatial patterns of water depth and velocity that are 2D in space and dynamic in time
- Until recently modelling of such flows has only been possible for small river reaches (10-50km)
- New opportunities
  - Large scale modelling has now been made possible by: Simplified 2D hydraulic models, Faster computers, New satellite data sources e.g. SRTM, satellite radars
- New satellite data sources e.g. SRTM, satellite radars
- Simplified 2D model pros
  - Floodplain flow is solved analytically rather than numerically so very efficient
  - 150-500k cells for full dynamic events should run in less than 1 day on a pc
  - Can use large elements (e.g. 250m 1000m grids)
  - Intrinsically mass conservative treatment of floodplain flow
- Simplified 2D model cons
  - Simplified floodplain flow representation
  - Wetting front propagation may be grid and time step dependent

## Example of hydraulic modelling of floodplains (II)







- TOPEX/Poseidon ground track coverage over Amazon
- Comparison of water levels derived from model and altimetry at two places

Courtesy: M. Wilson et al. http://swot.jpl.nasa.gov/

## From raw data sets to information in the hydrological context (I)

- Satellite altimetry is a piece of the complex hydrology puzzle
- Understanding, monitoring, assessing in the hydrology context needs an engineering approach
- It cannot be in isolation, team approach is essential with all relevant players aboard, including final users
- It is important to be aware about potential limitations, accuracy, processing methods of the various data sets as well as their availability and sustainability in the future
- Modelling tools are necessary to integrate data sets and provide finer resolution in space and time
- The application of satellite altimetry in small water bodies is still at research stage as opposed to oceans or large lakes where it is much more consolidated
- The main reason is that in small water bodies a more sophisticated processing is necessary

## From raw data sets to information in the hydrological context (II)

#### Many data sets

- Many sources: In-situ, satellite, data bases, etc.
- Various types: Meteorological, socioeconomic, etc.
- Many variables: water level, flood area/volume, snow cover, glaciers, frozen ground...
- Water fluxes: precipitation, evaporation, transpiration, snow melt, soil water depletion, river discharge, etc.

#### Growing complexity of satellite data sets

- No water variables available in these data files
- Specific processing chains to extract information relevan to water
- Space and time resolution as well as coverage not immediate to understand
- Differences between products (e.g. L1, L2)
- Differences between missions

## From raw data sets to information in the hydrological context (III)

- Many users, e.g.,
  - Universities/Research Centers
  - Water Authorities, Water Operators, Private Companies,
  - International Organisations, NGOs,

#### Many applications, e.g.,

- Water Resource Management
- Environment Monitoring,
- Disaster Monitoring
- Agriculture
- Etc.

#### Many regions of interest

E.g., Global, Trans-boundary, etc.

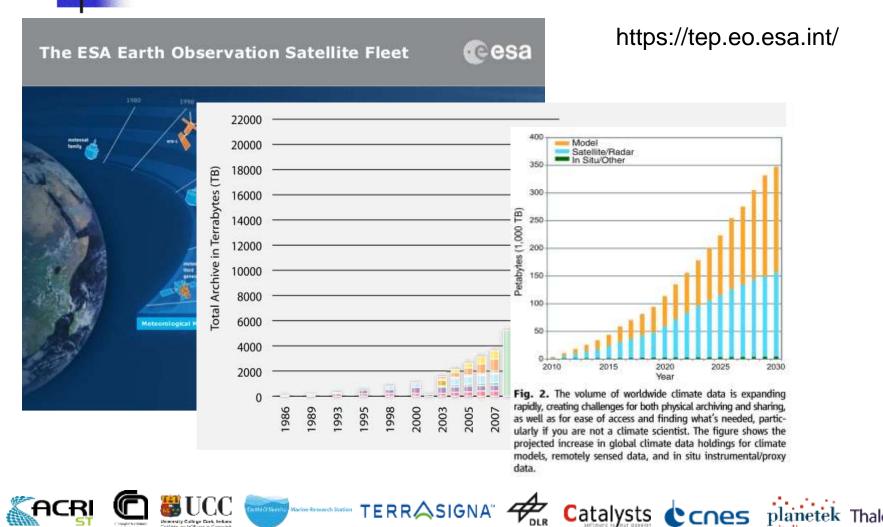
#### Many types of analysis

- E.g., Climate Change, Water Cycle studies
- Many domains
  - e.g. floods, droughts, hydropower, irrigation, etc.

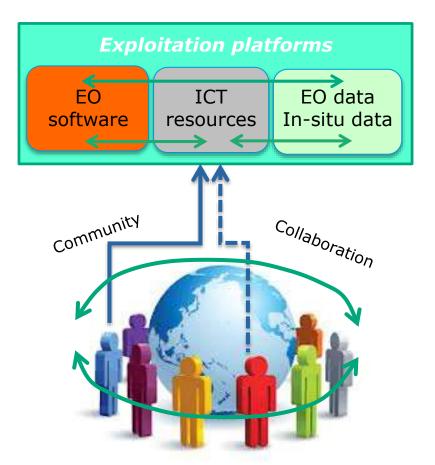
#### The state-of-the-art

- Uploading and processing of satellite data sets in hydrological model is not easy to do
- Accessing to all available satellite data sets, services and toolboxes for hydrology is not user-friendly
- Integration of datasets, services and toolboxes is now possible for a limited number of people
- Comparison of results between different groups is not easy missing a common processing protocol
- People spend lot of time in IT tasks
- People do not have the necessary IT resources at their laboratories
- The three pillars of the hydrology community
  - Having room where to share information, knowledge, algorithms, tools, results, products, services, etc.
  - Having a portal providing data sets and services tailored for hydrological applications
  - Having functionalities to discover, access, process, visualise, and compare various datasets as well as integrate their own hydrological models and data

# A paradigm change with the development of thematic platforms



### What is a Thematic Exploitation Platform?





## **Bringing together**

- EO data
- In-situ data
- Computing resources & hosted processing
- Processing tools
- Collaboration mechanisms





















### **Exploitation Platforms for different** communities

ESA is currently implementing seven Thematic Exploitation Platforms (TEPs), in support of seven thematic communities:

- Coastal
- **Forestry**
- Geohazards
- Hydrology
- Polar
- Urban











coastal tep



polar tep





geohazards tep



forestry tep























## **Coastal Thematic Platform**



Unlocking coastal knowledge and innovation using satellite imagery and cloud processing

https://coastal-tep.eo.esa.int/



Eimear Tuohy, MaREI, UCC eimear.tuohy@ucc.ie

## Thematic hydrology platform 0



https://hydrology-tep.eo.esa.int/

- A set of services based mainly on the exploitation of different satellite datasets and tools that will be available to the hydrology community
- The aim of these services is to make easier the access, exploitation, processing and visualization of different type of datasets (satellite, insitu, socioeconomic databases) to the expert and non expert users
- Examples of services include water resource management, floods monitoring, drought monitoring, etc.
- The platform responds to the need for integrated and open access to different areas and categories of users (government decision makers, scientists, businesses and citizens)
- These needs are particularly high in the developing countries where there is not enough ground truth data coverage
- The platform brings together IT tools, cloud processing, data sets and services tailored to the hydrology community requirements
- The platform should enable the inclusion of satellite datasets in existing and new decision support tools for water managers and decision makers

## The new concept



https://hydrology-tep.eo.esa.int/



Source: ESA

- Hidrological services that will be implemented:
  - Flood monitoring and small water bodies mapping
  - Water quality and level
  - Hydrological modelling

## Final comments (I)

- While the demand on water continues to grow, more and more catchments are becoming ungauged as in-situ gauges falls out of repair
- Using the remote measurement capability of altimetry, it is now possible for water resource managers to access some data and its context decadal historical information
- The technology can be applied as well in the oceanic coastal zone (similar difficulties in retrieval due to contamination by surrounding land)
- The scientific challenge is to fully extend to the global inland water bodies the success of altimetry in monitoring the global open ocean.
- To satisfy hydrologist requirements we need:
  - Improve the processing (that is work in progress)
  - better spatial/temporal sampling (SWOT or constellations)
  - integration of measurements and synergy with modelling tools (thematic processing platforms)

# Final comments (II)

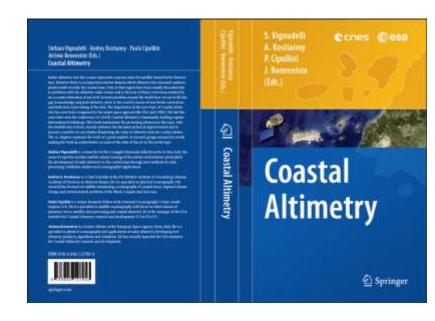
- Landsat imagery and satellite radar altimetry can be combined over a period of several years
- This fusion process provides several related products, including the estimation of water volume changes and bathymetry
- However, the practical use of this multi-sensor approach requires a proper quantification of the error sources
- Lake Nasser was an especially appropriate test site for the exploitation of the fusion of Landsat and radar altimetry in the Sahara region, and areas suffering from water scarcity in general, which make use of large surface reservoirs
- I will show results from this case-study tomorrow



## "Inland Water Altimetry" a Springer Book in progress that complements the "Coastal Altimetry" book

Editors: Benveniste (ESA), Vignudelli (CNR, Italy), Kostianoy (SIO, Russia)

- 19 chapters
- Tens of people involved in authoring
- Chapter 18 "Fusion of Radar Altimetry with Imaging Satellites for Monitoring Water Volume Changes" by R. Abileah, S. Vignudelli, A. Scozzari



https://sites.google.com/site/hydrospacebook/home



## Authors: Ron Abileah (JomegaK), Andrea Scozzari and Stefano Vignudelli (CNR)

Envisat RA-2 Individual Echoes: a unique dataset for a better understanding of inland water altimetry potentialities



even with a relatively live pulse repetition frequency, to analyze the pseudiarities of actual eigenit for detecting and ranging small water excluses. In particular, the RS-2 instrument offers a global artitive of Individual School (Ex), collected at the native verying rate at 1790 Hz, in addition to the 198's data obtained by insolvered averaging, which are hydrally delivered to the users as standard products. EA-2 shores with below today platforms the benefit a continuous and interferred profiling working, on it was recommended by the scientific community in designing most relatives' exponencests. This is a facther reason to consider the sauge of NA-2 We asreticularly attractive. Hithist only available for a small personings of the cartir's various, software If data exist in order to shady the beight serviced capability of these veloces, in particular for what concern canal scates haden, where we done that enough common is exhibited for housing substice's narrow nations and range them correctly. A psychiat papert of this work has in the assumption that must of the rotateod school and specular. A theoretical framework to developed according to this assumption, which is validated by investigating real RA-2 data and observing their related specialize trainings. In particular, we discuss here appealize schools are expected to be very contrain to inland ablessive, and are reset often associated with small to reading over lakes and tivers. This paper illustrates the expected electromagnetic betanious of specular water targets by exploiting the classical value cross-section (BCD) thater his secondar parties is Beselfe from the model, are compared, with real IE date in these solution association, regarding two streets of vortable width and one fixed plate, in order to check additional hydrological regimes. The model very riviely matches the data in all cases, making the results of this validation activity very promising. In particular, we demonstrate the bookbility of using satellite natural travety in river much emplier than what was considered possible until now.

Keywords Irland weter aftentry, Columnia, Doppler processing. Ereinst. Individual Edward

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